

Special relativity

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(Dated: March 21, 2023)

Video:

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I. PHYSICAL LAWS AS THE FUNCTIONS OF THE SCALE OF OBSERVATION

Newton's equation $F = ma$ is modified at $v \sim c = 2.9979 \cdot 10^8 m/s$ (speed of light)

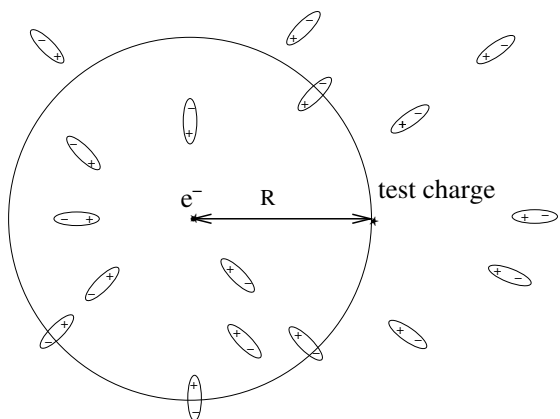
Problem: our intuition belongs to $\frac{v}{c} \ll 1$

The observed quantities and the physical laws depend on the scale of observation

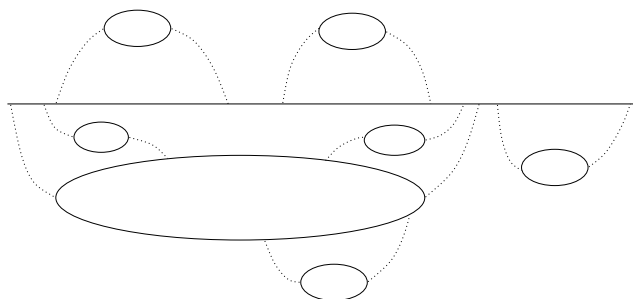


Scales: L, T, and M

Charge:



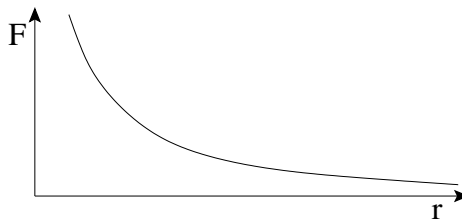
Polarizable medium



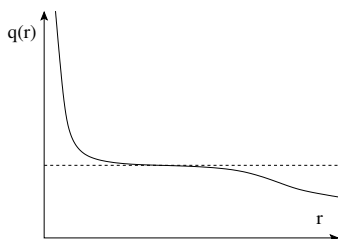
Relativistic vacuum

$$F_C(r) = \frac{qq'}{r^2} \neq F_{phys}(r) = \frac{q(r)q'}{r^2}$$

Vacuum polarization: $q \rightarrow q(r)$



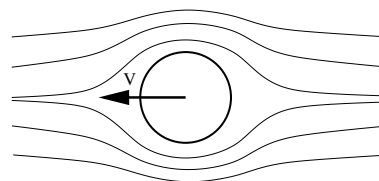
Physical constant \equiv plateau



Mass:

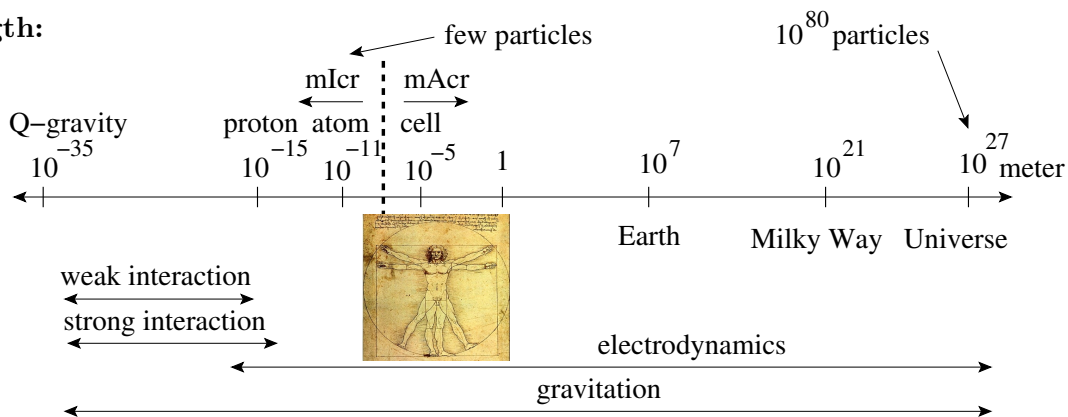
$$E(v) = E(v_0) + (v - v_0) \frac{dE(v_0)}{dv} + \frac{(v - v_0)^2}{2} \frac{d^2 E(v_0)}{dv^2} + \dots$$

$$M(v_0) = \frac{d^2 E(v_0)}{dv^2}$$



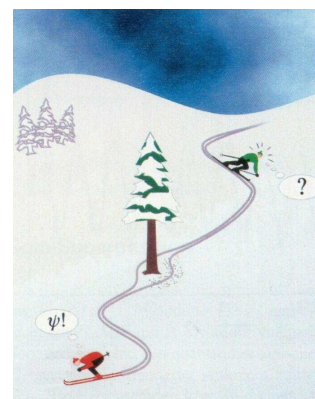
Interactions with the environment \implies effective parameters: $q \rightarrow q(r)$, $M \rightarrow M(v)$, etc.

Length:



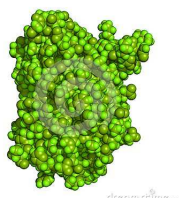
Quantum mechanics:

- The Reality can not fully be known
- Quantum mechanics:
 - Optimized and consistent treatment of partial information
- Quantum state: a list of virtual realities
 - like a phone book: name \leftrightarrow virtual reality
 - tel. number \leftrightarrow probability



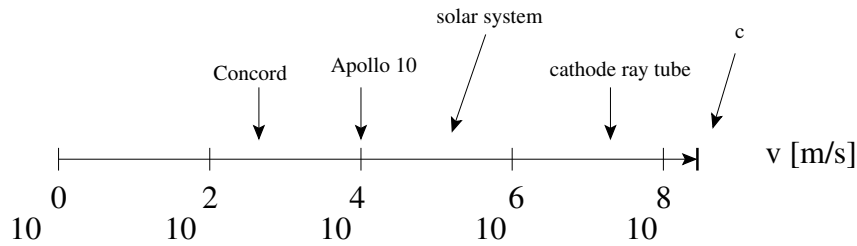
Life:

- elementary unit: protein
- living forms consist of 4500 proteins
- Origin: primordial soup?
 - 4^{165} possible RNA chains
 - $M = 2 \times 10^{77} \text{ kg} \sim M_{Universe} \times 10^{25}$



450 randomly chosen proteins
at the quantum-classical border
Quantum origin of life?

Velocity:



Orders of magnitudes in free fall: $v = 9.8t[MKS]$,

after 1 year $v = 9.8 \times 365 \times 24 \times 3600 \approx 3 \times 10^8 m/s$

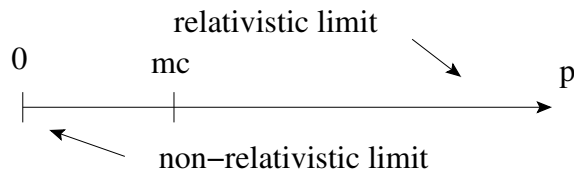
Momentum:

measure of “relativisticness“:

one needs dimensionless ratios

$$0 < \frac{v}{c} < 1$$

$$0 < \frac{p}{mc} < \infty \text{ with crossover at } \frac{p}{mc} \sim 1$$



II. A CONFLICT AND ITS SOLUTION

A. Reference frame and Galilean symmetry

Inertial reference frame: free motion = constant velocity

$$\mathbf{x} = t\mathbf{v} + \mathbf{x}_0$$

$$\text{E. O. M.: } \ddot{\mathbf{x}} = 0$$

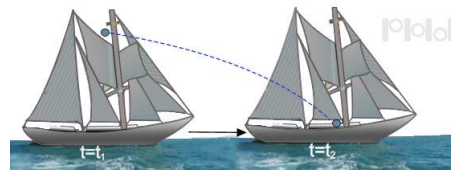
identical in each inertial reference frame

Galilean relativity: a generalization of the dynamics of a free particle to the interactive case

The mechanical laws are identical in each inertial reference frame

Example:

An object, falling freely from the the mast, ends up at the bottom of the mast on a ship which moves with constant velocity.



Symmetry transformations of Newton’s equation: $m \frac{d^2 \mathbf{x}}{dt^2} = 0$: (Galilean transformations)

$$t \rightarrow t' = t + t_0 \quad \leftarrow \text{absolute time}$$

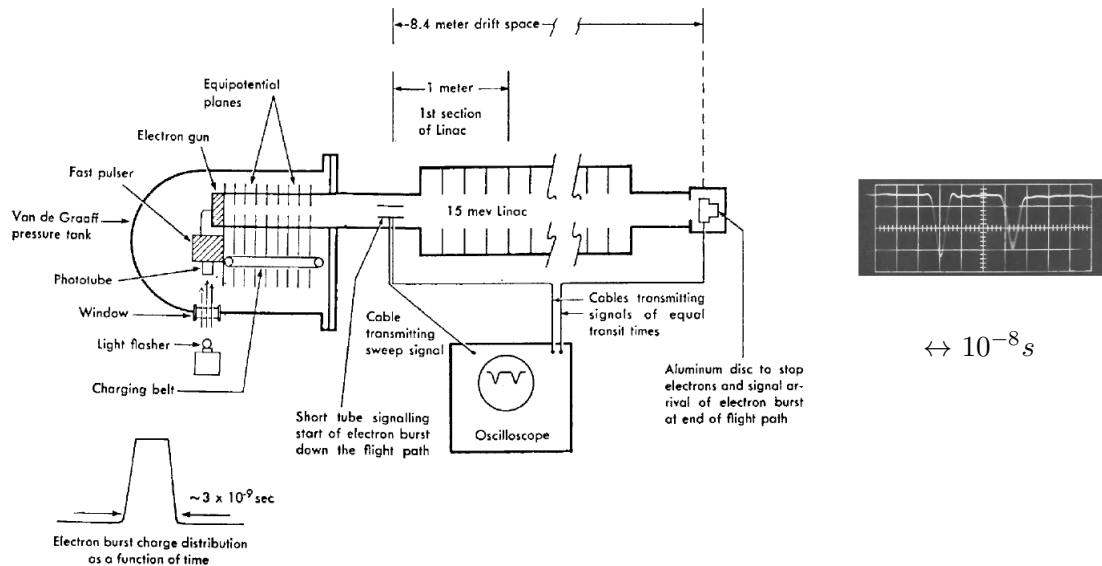
$$\mathbf{x} \rightarrow \mathbf{x}' = R\mathbf{x} - t\mathbf{v} + \mathbf{x}_0$$

Different reference frames are connected by Galilean transformations.

Addition of the velocity: $\dot{\mathbf{x}} \rightarrow \dot{\mathbf{x}}' = \frac{d}{dt}(\mathbf{x} - t\mathbf{v} + \mathbf{x}_0) = \dot{\mathbf{x}} - \mathbf{v}$ (absolute time)

B. Limiting velocity

W. Bertozzi, Am. J. Phys. **32** 551 (1964)

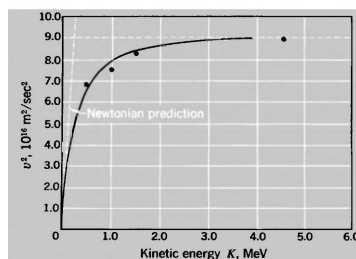


Energy K [MeV]	Time of flight t [10^{-8} s]	Velocity v [10^8 m/s]	Velocity square v^2 [10^{16} m ² /s ²]
0.5	3.23	2.60	6.8
1.0	3.08	2.73	7.5
1.5	2.92	2.88	8.3
4.5	2.84	2.96	8.8
15	2.80	3.00	9.0

as the energy increases like $E \rightarrow 30E$

energy conservation requires $K \rightarrow 30K$

Newton's equation: $v^2 \rightarrow 30v^2$?



Limiting velocity: $v < c$ (not enough energy to accelerate beyond c)

C. Particle or wave?

XIX.-th century physics: nature of light

- Thomas Young (1801-04): measurement of interference

- Augustin-Jean Fresnel (1818): explication of interference, diffraction, polarization

- James Clerk Maxwell (1861): electrodynamics

Wave: diffraction, interference, polarization ↔ Particle: energy-momentum

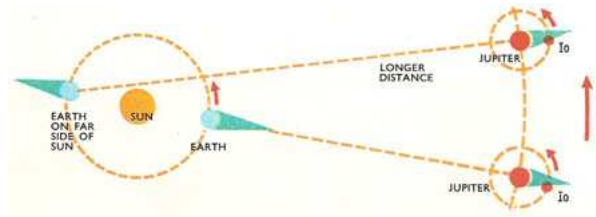
Mechanical models until 1850 but the speed of light is too high for a particle

Speed of light :

Ole Roemer (1675): eclipse of Jupiter's

moons varies in time

$$c \approx 2 \times 10^8 \text{ m/s}$$

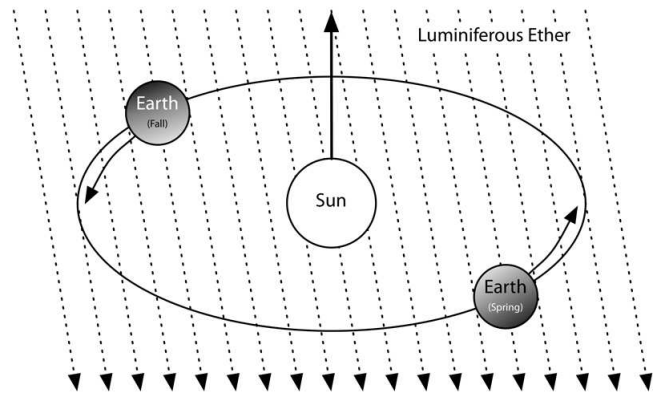


Wave or particle?

Particle: $v_{part} = v_{source} + v_{light}$,

Wave: v_{wave} is fixed within the medium

Ether hypothesis →



How to find our velocity with respect to the ether?

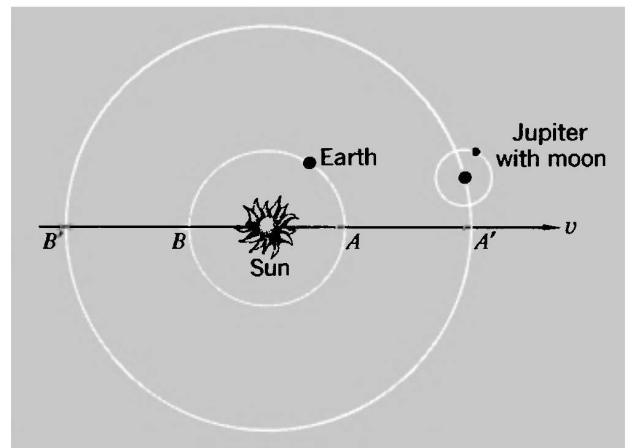
Maxwell: 1 Jupiter year=12 Earth years,

two measurements, separated by 6 years

$$t_A^{écl.} = \frac{l}{c + v_{sol}}, \quad t_B^{écl.} = \frac{l}{c - v_{sol}}$$

$$t_B^{écl.} - t_A^{écl.} = \frac{2lv_{sol}}{c^2 - v_{sol}^2} = \frac{2lv_{sol}}{(c + v_{sol})(c - v_{sol})}$$

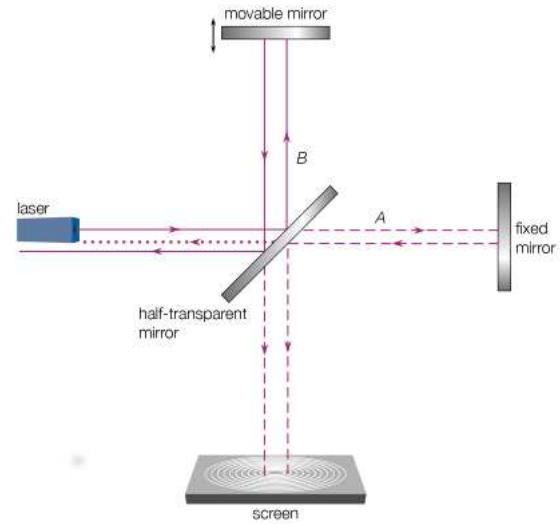
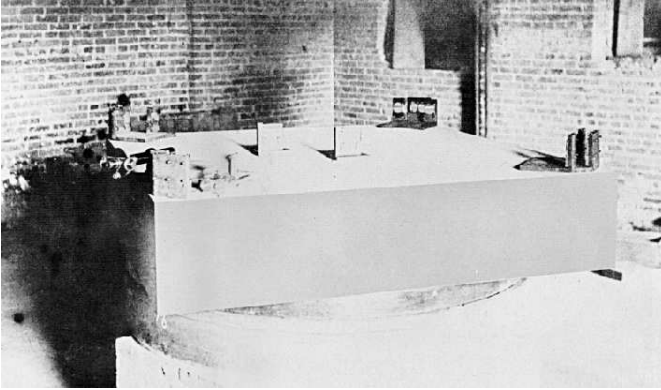
$$\approx \frac{2lv_{sol}}{c^2} = \underbrace{t_0}_{16min} \frac{2v_{sol}}{c}$$



The problem is the repetition of the same experience 6 years later

D. Propagation of the light

Michelson (1881):



$$t_{\parallel} = \frac{\ell_{\parallel}}{c-v} + \frac{\ell_{\parallel}}{c+v} = \frac{2c\ell_{\parallel}}{c^2-v^2} = \frac{\frac{2\ell_{\parallel}}{c}}{1-\frac{v^2}{c^2}}$$

$$\left(\frac{ct_{\perp}}{2}\right)^2 = \ell_{\perp}^2 + \left(\frac{vt_{\perp}}{2}\right)^2, \quad t_{\perp}^2(c^2-v^2) = 4\ell_{\perp}^2, \quad t_{\perp} = \frac{2\ell_{\perp}}{\sqrt{c^2-v^2}}$$

$$\Delta t(\ell_{\parallel}, \ell_{\perp}) = t_{\parallel} - t_{\perp} = \frac{2}{c} \left(\frac{\ell_{\parallel}}{1-\frac{v^2}{c^2}} - \frac{\ell_{\perp}}{\sqrt{1-\frac{v^2}{c^2}}} \right) = \frac{2}{c} \frac{\ell_{\parallel} - \ell_{\perp} \sqrt{1-\frac{v^2}{c^2}}}{1-\frac{v^2}{c^2}}$$

Rotation by 90° within few minutes:

$$\Delta t'(\ell_{\parallel}, \ell_{\perp}) = -\Delta t(\ell_{\perp}, \ell_{\parallel}) = \frac{2}{c} \frac{\ell_{\parallel} \sqrt{1-\frac{v^2}{c^2}} - \ell_{\perp}}{1-\frac{v^2}{c^2}}$$

$$\Delta t(\ell_{\parallel}, \ell_{\perp}) - \Delta t'(\ell_{\parallel}, \ell_{\perp}) = \frac{2}{c} \frac{(\ell_{\parallel} + \ell_{\perp})(1 - \sqrt{1-\frac{v^2}{c^2}})}{1-\frac{v^2}{c^2}}$$

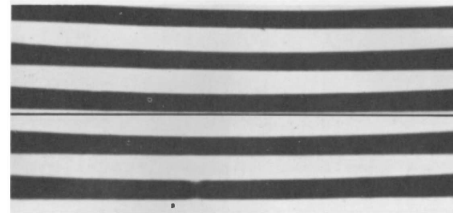
$$\sqrt{1+\epsilon} \sim 1 + \frac{\epsilon}{2} \rightarrow \approx \frac{2(\ell_{\parallel} + \ell_{\perp})}{c} \frac{\frac{v^2}{2c^2}}{1-\frac{v^2}{c^2}} \approx (\ell_{\parallel} + \ell_{\perp}) \frac{v^2}{c^3}$$

The mirrors are not exactly perpendicular \implies interference rings

Number of shifted lines: ΔN

$$\Delta \ell = \lambda \Delta N = (\Delta t - \Delta t')c$$

$$\Delta N = (\Delta t - \Delta t') \frac{c}{\lambda} = \frac{v^2}{c^2} \frac{\ell_{\perp} + \ell_{\parallel}}{\lambda}$$

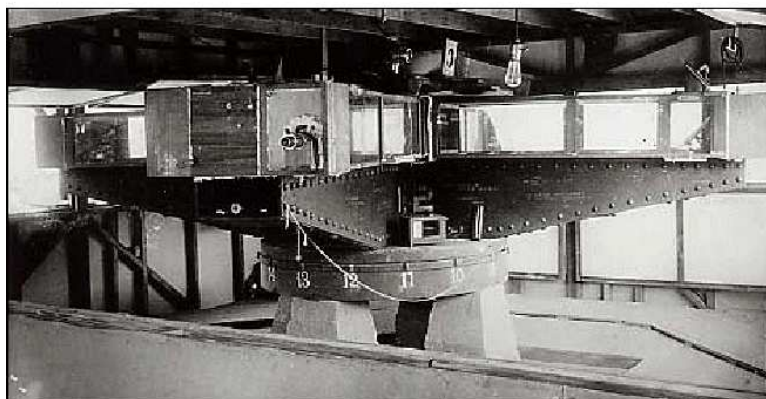
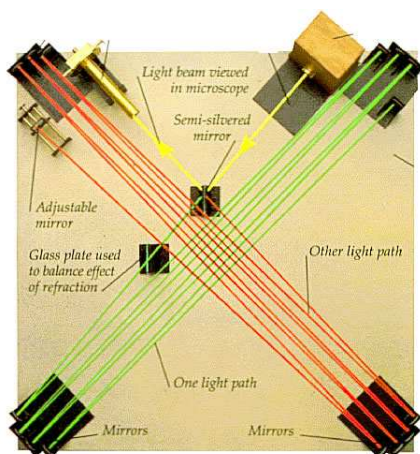


Assuming $v_{Earth} = 30 \text{ km/s}$, $\frac{v}{c} \approx 10^{-4}$ and

using $\lambda = 6 \times 10^{-7} \text{ m}$, $\ell = 1.2 \text{ m} \implies \Delta N \approx 0.04$ was not found

No way to measure absolute velocity in physics

Michelson-Morley (1887): $\ell \rightarrow 10\ell$, $\Delta N \rightarrow 0.4$, $\Delta N_{obs} = 0 \pm 0.005$



Fitzgerald Lorentz (1892): a mysterious contraction of solids in motion:

$$l \rightarrow l\sqrt{1 - \frac{v^2}{c^2}}, \Delta t = 0 \text{ for } l_{\perp} = l_{\parallel}$$

Einstein (1905): contraction follows from the way one measures the length

Kennedy Thorndike (1932): null result with $l_{\perp} \neq l_{\parallel}$

E. The problem and its solution

The light is of the nature particle or wave?

Particle: $v_{part} = v_{source} + v_{emission}$, but $c \neq v_{source} + c$?

Wave: v_{onde} est fixed, but Michelson-Morley ?

The addition of the velocity do not apply to light?

One of the following seemingly natural assumptions is wrong:

1. The physical laws assume the same form in each reference frame.
2. The time is absolute.

Einstein (1905): No justification of point 2.

Special relativity: The physical laws assume the same form in each reference frame.

Results:

1. The speed of light is fixed by Maxwell's equations.
2. The coordinate and the velocity can be given relative to some reference object.
3. The acceleration and the derivatives $\frac{d^n \mathbf{x}(t)}{dt^n}$, $n \geq 2$ are absolute.

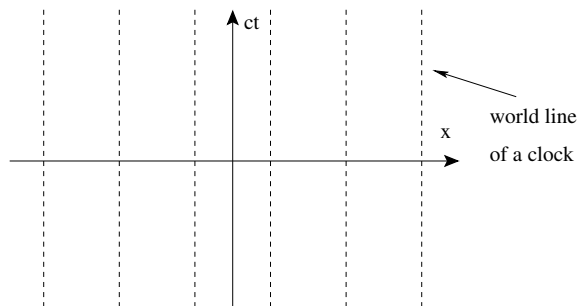
General relativity: The coordinates, together with all derivatives, $\frac{d^n \mathbf{x}(t)}{dt^n}$, are relative.

A more careful analysis of the measurement of the coordinates and the time is needed.

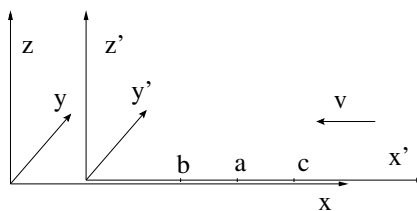
Distance: with a reference meter rod
(macroscopic!)



Time: synchronized standard clock
at each space point



Simultaneity is relative:
a light signal $b \leftarrow a \rightarrow c$



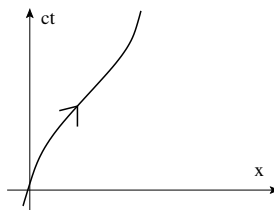
III. SPACE-TIME

A. World line

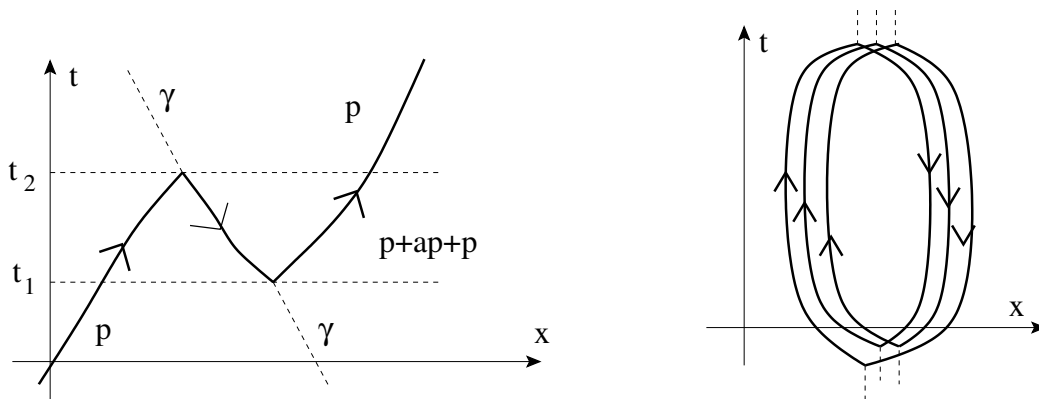
Non-relativistic motion: trajectory: $\mathbf{x}(t)$

Relativistic motion: world line: $x^\mu(s) = (ct(s), \mathbf{x}(s))$, $\mu = 0, 1, 2, 3$.

Non-relativistic motion:



New possibility: world line \implies trajectory



length s : ordering the events

Universe of a single fermion

Anti-particle: $t \rightarrow -t \leftrightarrow E \rightarrow -E$

Classical mechanics: $\frac{dp}{dt} = -\frac{\partial H(p,q)}{\partial q}, \frac{dq}{dt} = \frac{\partial H(p,q)}{\partial p}$

Quantum mechanics: $i\hbar\partial_t\psi = H\psi$

Quantum field theory: $E \geq 0$

Giving up classical E.O.M.:

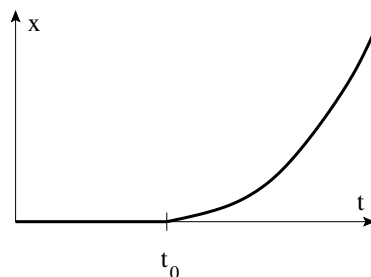
- Sufficient condition for locally unique solution:

$$\dot{x}(t) = f(x, t), \quad x(t_i) = x_i$$

is the continuity of $\partial_x f(x, t)$

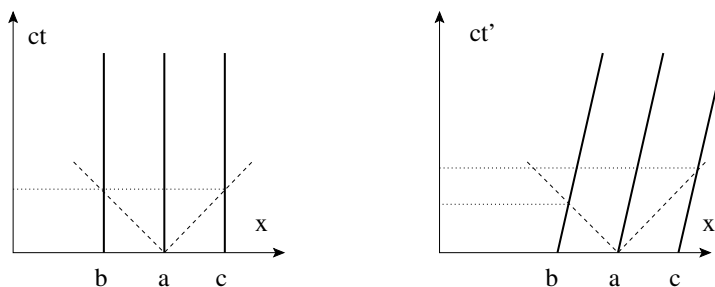
- Example:

$$\begin{aligned} \dot{x} &= g|x|^p, \quad 0 < p < 1 \\ x(t) &= \alpha t^\beta, \quad \alpha\beta t^{\beta-1} = g(\alpha t^\beta)^p \\ \beta - 1 &= \beta p, \quad \beta = \frac{p}{1-p} \\ \alpha\beta &= g\alpha^p, \quad \frac{p\alpha}{1-p} = g\alpha^p, \quad \frac{p}{g(1-p)} = \alpha^{p-1} \\ x(t) &= \begin{cases} 0 & t < t_0, \\ \left[g \left(\frac{1}{p} - 1 \right) (t - t_0) \right]^{\frac{1}{1-p}} & t \geq t_0, \end{cases} \end{aligned}$$



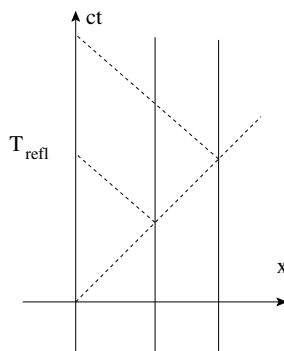
t_0 is not determined by the initial condition, pair creation is quantum phenomenon

Relative simultaneity:



Clock synchronization:

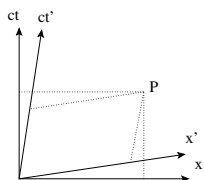
1. reference clock at $x = 0$
2. light signal from $(ct, x) = 0$
3. time at reflection: $t(x)$
4. time of return to $x = 0$: $T(x)$
5. $\Delta t = \frac{T(x)}{2} - t(x)$



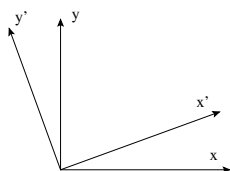
B. Lorentz transformation

Transformation between two reference frame: $(ct, \mathbf{x}) \rightarrow (ct', \mathbf{x}')$

Non-orthogonal axes

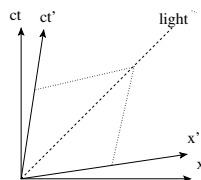


Euclidean rotation



No fixed line

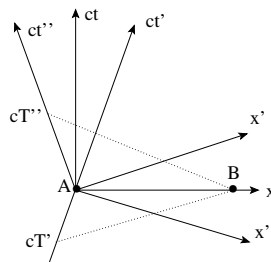
Lorentz Transformation



Light: a fixed line

Simultaneity is relative:

$$T'(B) - T'(A) < T(B) - T(A) = 0 < T''(B) - T''(A)$$



General form:

$$x' = ax - bct$$

boost:

$$= a(x - vt)$$

inverse ($v \rightarrow -v$):

$$x = a(x' + vt')$$

Applied for the propagation of the light $x = ct, x' = ct'$

$$ct' = a(c - v)t, ct = a(c + v)t' \implies ct = a(c + v)\frac{a}{c}(c - v)t, a^2 = \frac{c^2}{c^2 - v^2}, a = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$x' = \frac{x - vt}{\sqrt{1 - \frac{v^2}{c^2}}}, \quad x = \frac{x' + vt'}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$t' = \frac{t - \frac{vx}{c^2}}{\sqrt{1 - \frac{v^2}{c^2}}} (\leftarrow x = ct), \quad t = \frac{t' + \frac{vx'}{c^2}}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$\frac{v}{c} \rightarrow 0$: Galilean transformations

No change in the orthogonal directions: $\mathbf{v} = (v, 0, 0), y = y', z = z'$

Lorentz (1904) : compensation

Einstein (1905): way of observation

Lorentz symmetry is obeyed by all interactions

C. Addition of the velocity

Two different reference frames: S and S' : $x_{\parallel} = \frac{x'_{\parallel} + ut'}{\sqrt{1 - \frac{u^2}{c^2}}}$, $x_{\perp} = x'_{\perp}$, $t = \frac{t' + \frac{ux'_{\parallel}}{c^2}}{\sqrt{1 - \frac{u^2}{c^2}}}$

$$\begin{aligned} \mathbf{v}' &= \frac{d\mathbf{x}'}{dt'} \rightarrow \mathbf{v} = \frac{d\mathbf{x}}{dt} \\ \Delta t \rightarrow \Delta x_{\parallel} &= \frac{(v'_{\parallel} + u)\Delta t'}{\sqrt{1 - \frac{u^2}{c^2}}}, \quad \Delta x_{\perp} = v'_{\perp}\Delta t', \quad \Delta t = \frac{(1 + \frac{uv'_{\parallel}}{c^2})\Delta t'}{\sqrt{1 - \frac{u^2}{c^2}}} \\ v_{\parallel} &= \frac{\Delta x_{\parallel}}{\Delta t} = \frac{v'_{\parallel} + u}{1 + \frac{uv'_{\parallel}}{c^2}} = \begin{cases} v'_{\parallel} + u & u, v'_{\parallel} \ll c \\ c & v'_{\parallel} \ll c, u \approx c, \text{ ou } u \ll c, v'_{\parallel} \approx c \end{cases} \\ v_{\perp} &= v'_{\perp} \frac{\sqrt{1 - \frac{u^2}{c^2}}}{1 + \frac{uv'_{\perp}}{c^2}} = \begin{cases} v'_{\perp} & u \ll c \\ 0 & u \approx c \end{cases} \end{aligned}$$

D. Invariant distance

Euclidean geometry: the invariance of $s^2 = (\mathbf{x}_2 - \mathbf{x}_1)^2$

identifies the symmetries (translations + rotations)

Minkowski geometry: the invariance of $s^2 = c^2(t_2 - t_1)^2 - (\mathbf{x}_2 - \mathbf{x}_1)^2$

identifies the symmetries (translations + Lorentz transformations)

Proof A: (by Lorentz transformation)

$$\begin{aligned} x' &= \frac{x - vt}{\sqrt{1 - \frac{v^2}{c^2}}}, \quad t' = \frac{t - \frac{vx}{c^2}}{\sqrt{1 - \frac{v^2}{c^2}}} \\ s^2 &= c^2t^2 - x^2 \rightarrow \frac{(ct - \frac{vx}{c})^2 - (x - vt)^2}{1 - \frac{v^2}{c^2}} = \frac{(c^2t^2 - x^2)(1 - \frac{v^2}{c^2})}{1 - \frac{v^2}{c^2}} = c^2t^2 - x^2 \end{aligned}$$

Proof B: (by consistency)

- $s^2 = 0$ the possibility of exchanging light signal is Lorentz invariant

- $s^2 \neq 0$? Three reference frames, S_0 and S_j , $\mathbf{v}_{S_0 \rightarrow S_j} = \mathbf{v}_j$, $j = 1, 2$, $|\mathbf{v}_1|, |\mathbf{v}_2| \ll c$

Step 1. $s_j^2 = F(|\mathbf{v}_j|, s_0^2)$

Step 2. $F(|\mathbf{v}|, 0) = 0$

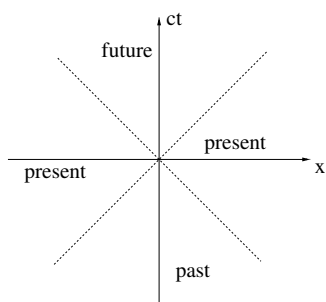
Step 3. continuity of $F(v, s^2)$ in s^2 at $s^2 = 0$: $ds_j^2 = F(|\mathbf{v}_j|, ds_0^2) \approx \underbrace{\frac{\partial F(|\mathbf{v}_j|, s^2)}{\partial s^2}}_{a(|\mathbf{v}_j|)} \Big|_{s^2=0} ds_0^2$

Step 4. $ds_j^2 = a(|\mathbf{v}_j|)ds_0^2$, $ds_2^2 = a(|\mathbf{v}_1 - \mathbf{v}_2|)ds_1^2$, $a(|\mathbf{v}_1 - \mathbf{v}_2|) = \frac{a(|\mathbf{v}_2|)}{a(|\mathbf{v}_1|)} \rightarrow a = 1$

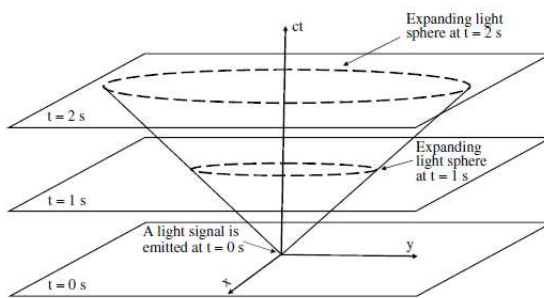
E. Minkowski geometry

Three different kinds of space-time intervals:

- time-like: $c^2(t_1 - t_2)^2 - (\mathbf{x}_1 - \mathbf{x}_2)^2 > 0$
- space-like: $c^2(t_1 - t_2)^2 - (\mathbf{x}_1 - \mathbf{x}_2)^2 < 0$
- light-like: $c^2(t_1 - t_2)^2 - (\mathbf{x}_1 - \mathbf{x}_2)^2 = 0$



past, present, future



Light cone

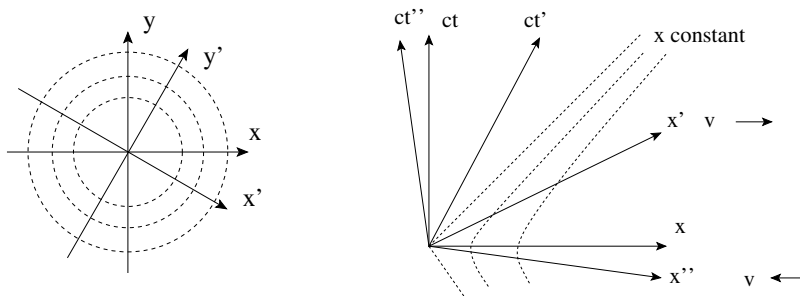
Change of scale:

Euclidean:

$$x^2 + y^2 = R^2$$

Minkowski:

$$(ct)^2 - x^2 = s^2$$



IV. PHYSICAL PHENOMENAS

A. Lorentz contraction of the length

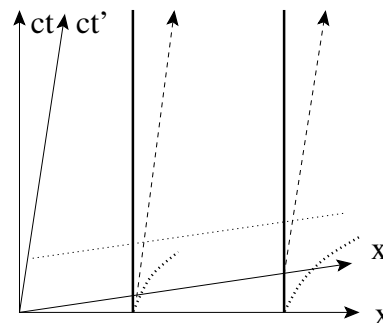
$$\ell = x_2 - x_1$$

$$\ell' = x'_2 - x'_1 \text{ simultaneous coordinates}$$

$$x_a = \frac{x'_a + vt'}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\ell = \frac{x'_2 - x'_1}{\sqrt{1 - \frac{v^2}{c^2}}} = \frac{\ell'}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\ell' = \ell \sqrt{1 - \frac{v^2}{c^2}}$$



A simple model: apparent rotation of a rectangular board

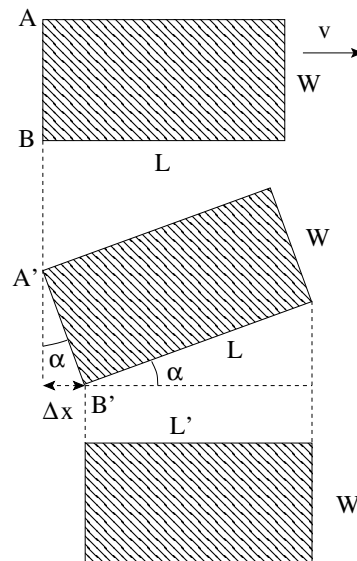
The light, propagating from A_0 and B_0 arrive at the **same time**:

$$\Delta t = \frac{W}{c}$$

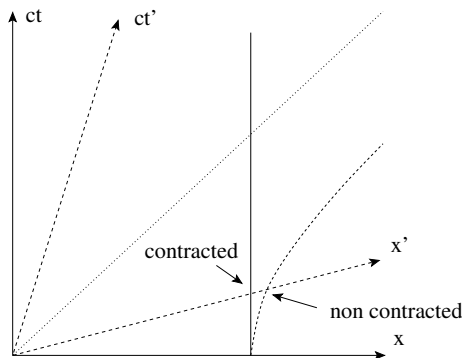
$$\Delta x = v\Delta t = W\frac{v}{c}$$

$$\sin \Theta = \frac{v}{c}, \quad \cos \Theta = \sqrt{1 - \frac{v^2}{c^2}}$$

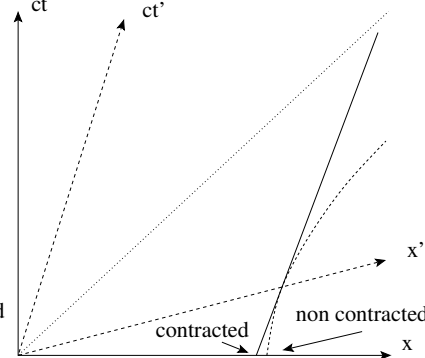
$$L' = L\sqrt{1 - \frac{v^2}{c^2}} \leftarrow \text{Lorentz contraction}$$



The contraction is relative:



Rod at rest



Moving rod

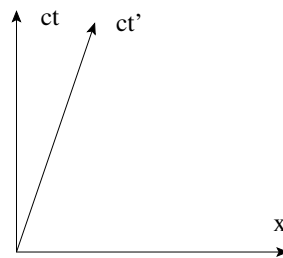
B. Time dilatation

Moving clock: Proper time: $t_0 = \frac{\sqrt{s^2}}{c}$

$$s^2 = c^2 t_0^2 = c^2 t^2 - x^2 = c^2 t^2 \left(1 - \frac{v^2}{c^2}\right)$$

$$t = \frac{t_0}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$t > t_0$: slowing down

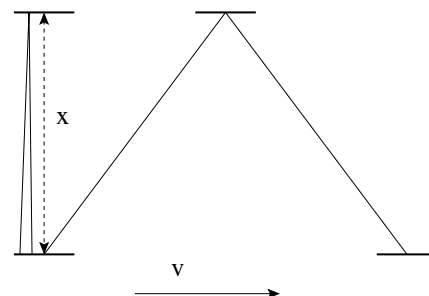


Optical clock:

$$c^2 t_0^2 = x^2$$

$$c^2 t'^2 = t'^2 v^2 + t_0'^2 c^2$$

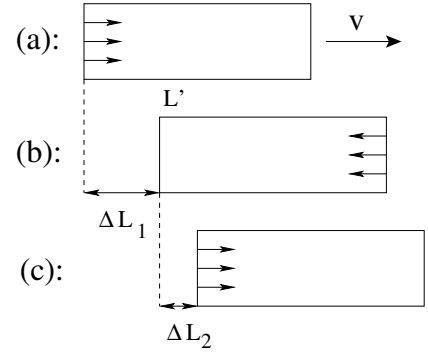
$$t' = \frac{t_0}{\sqrt{1 - \frac{v^2}{c^2}}}$$



Time dilatation \implies Lorentz contraction

Moving rod with mirrors:

$$\begin{aligned}
 c\Delta t_1 &= \ell + v\Delta t_1 \\
 c\Delta t_2 &= \ell - v\Delta t_2 \\
 2t' &= \Delta t_1 + \Delta t_2 \\
 &= \frac{\ell'}{c-v} + \frac{\ell'}{c+v} = \frac{2\ell'c}{c^2 - v^2} \\
 t' &= \frac{\ell'}{c} \frac{1}{1 - \frac{v^2}{c^2}} \\
 \ell' = \ell_0 \sqrt{1 - \frac{v^2}{c^2}} &\leftrightarrow t' = \frac{t_0}{\sqrt{1 - \frac{v^2}{c^2}}} \quad \text{for } \ell_0 = t_0 c
 \end{aligned}$$

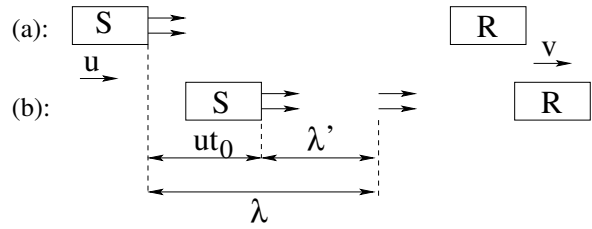


C. Doppler effect

Non-relativistic: sound velocity: w

Following one cycle:

$$\begin{aligned}
 w\Delta t &= \lambda' + u\Delta t \\
 \lambda' &= (w - u)\Delta t = \frac{w - u}{\nu} = \frac{w - v}{\nu'} \\
 \nu' &= \nu \frac{w - v}{w - u}
 \end{aligned}$$

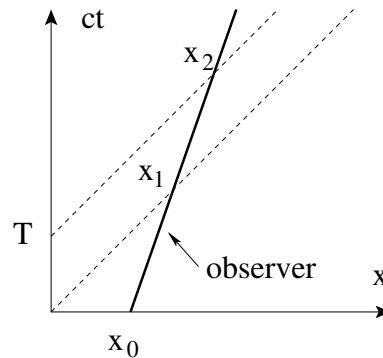


Stationary source: $u = 0$, $\nu' = \nu \left(1 - \frac{v}{w}\right)$, $\nu' = 0$ for $v = w$

Stationary receiver: $v = 0$, $\nu' = \frac{\nu}{1 - \frac{u}{w}}$, $\nu' = \infty$ for $u = w$

Relativistic (light): Two pulses with time difference T , speed of the detector is v

$$\begin{aligned}
 x_1 &= ct_1 = x_0 + vt_1 && \rightarrow t_1 = \frac{x_0}{c - v} \\
 x_2 &= c(t_2 - T) = x_0 + vt_2 && \rightarrow t_2 = \frac{x_0 + cT}{c - v} \\
 t_2 - t_1 &= \frac{T}{1 - \frac{v}{c}}, && x_2 - x_1 = \frac{vT}{1 - \frac{v}{c}}
 \end{aligned}$$



$$\begin{aligned}
 T' = t'_2 - t'_1 &= \frac{t_2 - t_1 - \frac{v}{c^2}(x_2 - x_1)}{\sqrt{1 - \frac{v^2}{c^2}}} \\
 &= \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}} \left(\frac{T}{1 - \frac{v}{c}} - \frac{v}{c^2} \frac{vT}{1 - \frac{v}{c}} \right)
 \end{aligned}$$

$$= \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}} \frac{T}{1 - \frac{v}{c}} \left(1 - \frac{v^2}{c^2}\right) = T \frac{\sqrt{1 - \frac{v^2}{c^2}}}{1 - \frac{v}{c}} = T \sqrt{\frac{1 + \frac{v}{c}}{1 - \frac{v}{c}}}$$

$$\nu' = \nu \sqrt{\frac{1 - \frac{v}{c}}{1 + \frac{v}{c}}} \neq \underbrace{\nu \left(1 - \frac{v}{c}\right)}_{\text{non-relativistic}}$$

Static gravitational field:

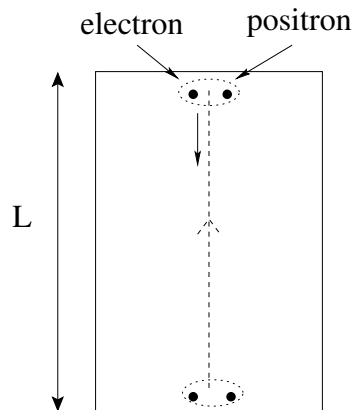
$$E_{\downarrow}(e^-e^+) = \underbrace{E_{\uparrow}(e^-e^+)}_{2mc^2} + 2m\Delta U$$

$$= E_{\uparrow}(e^-e^+) \left(1 + \frac{\Delta U}{c^2}\right)$$

$$E_{\uparrow}(e^-e^+) = E_{\uparrow}(\gamma), \quad E_{\downarrow}(e^-e^+) = E_{\downarrow}(\gamma)$$

$$\frac{E}{\omega_{\uparrow}} = \frac{\hbar\omega}{E_{\uparrow}(e^-e^+)} = 1 + \underbrace{\frac{\Delta U}{c^2}}_z$$

$$z = \frac{\Delta U}{c^2}$$



Time-dependent gravitational field:

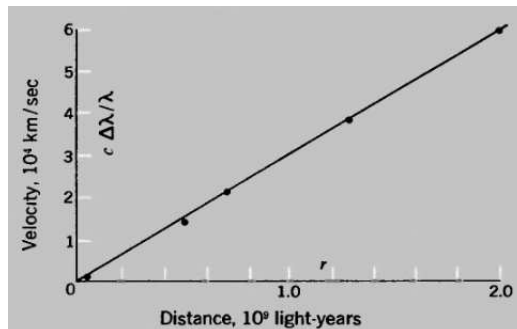
Robertson-Walker model of the Universe

Universe in expansion: $\lambda_{em} < \lambda_{obs}$

Red shift: $\frac{\omega_{em}}{\omega_{obs}} = \frac{\lambda_{obs}}{\lambda_{em}} = 1 + z > 1$

Hubble constant: $z = \frac{H}{c} \ell$

age of the Universe: $T_U = \frac{1}{H}, z = \frac{\ell}{T_U}$

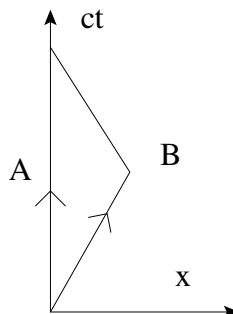


D. Paradoxes

Twins:

A: rests, B: leaves and returns

Which one is older when they meet again?

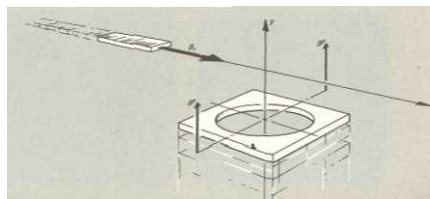


A rod and a circle:

$$l = 2r, \mathbf{v}_b = (u, 0, 0), \mathbf{v}_c = (0, v, 0)$$

$t = 0$: the center of the rod and
the origin of the circle coincide

Can they cross each other?



A spear and a stable:

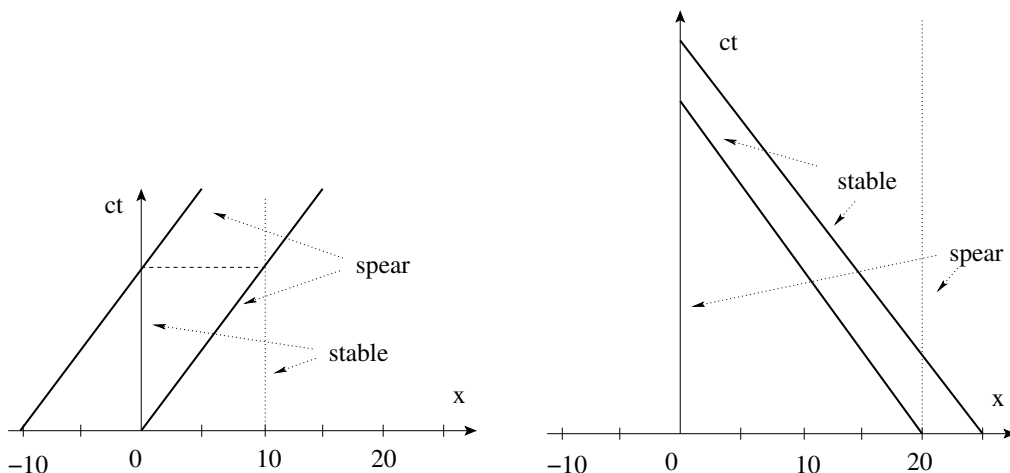
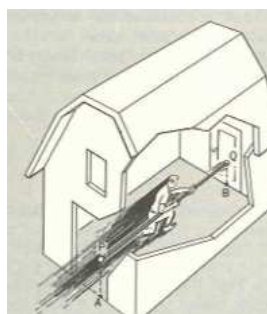
$$l_{spear} = 20m, l_{stable} = 10m$$

$$\sqrt{1 - \frac{v^2}{c^2}} = \frac{1}{2}$$

Reference frame of the stable: $l'_{spear} = 10m$

Reference frame of the spear: $l'_{stable} = 5m$

Can the spear enter into the stable?



V. VARIATIONAL FORMALISM OF A POINT PARTICLE

Need of an equation of motion which is independent of the choice of the coordinate system.

A. A point on a line

Goal: an equation to identify $x_{cl} \in \mathbb{R}$: use a function with extreme at c_{cl} only

$$S(x) \rightarrow \frac{dS(x)}{dx} \Big|_{x=x_{cl}} = 0$$

Reparametrization of the line (change of coordinate system): $x \rightarrow y$

$$\frac{dS(x(y))}{dy} \Big|_{y=y_{cl}} = \underbrace{\frac{dS(x)}{dx} \Big|_{x=x_{cl}}}_{0} \frac{dx(y)}{dy} \Big|_{y=y_{cl}} = 0$$

Variational principle, an alternative definition: $x \rightarrow x + \delta x$

$$\begin{aligned} S(x_{cl} + \delta x) &= S(x_{cl}) + \delta S(x_{cl}) \\ &= S(x_{cl}) + \delta x \underbrace{S'(x_{cl})}_0 + \frac{\delta x^2}{2} S''(x_{cl}) + \mathcal{O}(\delta x^3) \\ \implies \delta S(x_{cl}) &= \mathcal{O}(\delta x^2) \quad (\text{manifestly coordinate independent}) \end{aligned}$$

B. Non-relativistic particle

$$x_{cl}(t_i) = x_i, x_{cl}(t_f) = x_f \implies x_{cl}(t)$$

Variational principle: $x(t) \rightarrow x(t) + \delta x(t)$, $\delta x(t_i) = \delta x(t_f) = 0$

$$\begin{aligned} S[x(\cdot)] &= \int_{t_i}^{t_f} dt L(x(t), \dot{x}(t)) \\ \delta S[x(\cdot)] &= \int_{t_i}^{t_f} dt L\left(x(t) + \delta x(t), \dot{x}(t) + \frac{d}{dt}\delta x(t)\right) - \int_{t_i}^{t_f} dt L(x(t), \dot{x}(t)) \\ &= \int_{t_i}^{t_f} dt \left[L(x(t), \dot{x}(t)) + \delta x(t) \frac{\partial L(x(t), \dot{x}(t))}{\partial x} \right. \\ &\quad \left. + \frac{d}{dt}\delta x(t) \frac{\partial L(x(t), \dot{x}(t))}{\partial \dot{x}} + \mathcal{O}(\delta x(t)^2) - \int_{t_i}^{t_f} dt L(x(t), \dot{x}(t)) \right] \\ &= \int_{t_i}^{t_f} dt \delta x(t) \underbrace{\left[\frac{\partial L(x(t), \dot{x}(t))}{\partial x} - \frac{d}{dt} \frac{\partial L(x(t), \dot{x}(t))}{\partial \dot{x}} \right]}_{=0} \\ &\quad + \underbrace{\delta x(t)}_0 \frac{\partial L(x(t), \dot{x}(t))}{\partial \dot{x}} \Big|_{t_i}^{t_f} + \mathcal{O}(\delta x(t)^2) \\ &= \mathcal{O}(\delta x(t)^2) \end{aligned}$$

Euler-Lagrange equation:

$$\boxed{0 = \frac{\partial L(\mathbf{x}, \dot{\mathbf{x}})}{\partial \mathbf{x}} - \frac{d}{dt} \frac{\partial L(\mathbf{x}, \dot{\mathbf{x}})}{\partial \dot{\mathbf{x}}}}$$

- Lagrangian:

$$L = T - U = \frac{m}{2} \dot{\mathbf{x}}^2 - U(\mathbf{x}) \quad \longrightarrow \quad m\ddot{\mathbf{x}} = -\nabla U(\mathbf{x})$$

- Generalized momentum:

$$\mathbf{p} = \frac{\delta L}{\delta \dot{\mathbf{x}}}, \quad \text{E-L equation: } \dot{\mathbf{p}} = \frac{\delta L}{\delta \mathbf{x}}$$

- Cyclic coordinate: $\frac{\delta L}{\delta x_{cycl}} = 0$, p_{cycl} conserved

- Energy: Legendre transf.,

$$H(\mathbf{p}, \mathbf{x}) = \mathbf{p}\dot{\mathbf{x}} - L(\mathbf{x}, \dot{\mathbf{x}}), \quad \mathbf{p} = \frac{\delta L}{\delta \dot{\mathbf{x}}} = m\mathbf{v}$$

$$= \mathbf{p} \frac{\mathbf{p}}{m} - \frac{m}{2} \left(\frac{\mathbf{p}}{m} \right)^2 + U(\mathbf{x}) = \frac{\mathbf{p}^2}{2m} + U(\mathbf{x}) = T + U$$

$$\dot{H} = \dot{\mathbf{p}} \dot{\mathbf{x}} + \mathbf{p} \ddot{\mathbf{x}} - \dot{\mathbf{x}} \frac{\partial L}{\partial \mathbf{x}} - \ddot{\mathbf{x}} \frac{\partial L}{\partial \dot{\mathbf{x}}} = \dot{\mathbf{p}} \dot{\mathbf{x}} + \mathbf{p} \ddot{\mathbf{x}} - \dot{\mathbf{x}} \dot{\mathbf{p}} - \ddot{\mathbf{x}} \frac{\partial L}{\partial \dot{\mathbf{x}}} = 0$$

Examples:

1. Particle moving on a curve, $y = f(x)$, on the (x, y) plane: $\dot{y} = f'(x)\dot{x}$

$$L = \frac{m}{2}(\dot{x}^2 + \dot{y}^2) - mgf(x) = \frac{m(x)}{2}\dot{x}^2 - mgf(x), \quad m(x) = m[1 + f'^2(x)]$$

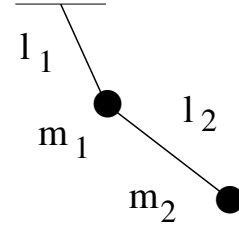
2. Pendulum:

$$L = \frac{m}{2}\ell^2\dot{\theta}^2 + mg\ell \cos \theta$$

3. Double pendulum:

$$\mathbf{x}_1 = \ell_1 \begin{pmatrix} \sin \theta_1 \\ -\cos \theta_1 \end{pmatrix}, \quad \mathbf{x}_2 = \mathbf{x}_1 + \ell_2 \begin{pmatrix} \sin \theta_2 \\ -\cos \theta_2 \end{pmatrix}$$

$$\dot{\mathbf{x}}_1 = \ell_1 \dot{\theta}_1 \begin{pmatrix} \cos \theta_1 \\ \sin \theta_1 \end{pmatrix}, \quad \dot{\mathbf{x}}_2 = \dot{\mathbf{x}}_1 + \ell_2 \dot{\theta}_2 \begin{pmatrix} \cos \theta_2 \\ \sin \theta_2 \end{pmatrix}$$



$$L = \frac{m_1 + m_2}{2} \ell_1^2 \dot{\theta}_1^2 + \frac{m_2}{2} \ell_2^2 \dot{\theta}_2^2 + m_2 \ell_1 \ell_2 \dot{\theta}_1 \dot{\theta}_2 (\cos \theta_1 \cos \theta_2 + \sin \theta_1 \sin \theta_2)$$

$$+ g(m_1 + m_2) \ell_1 \cos \theta_1 + g m_2 \ell_2 \cos \theta_2$$

$$0 = m_2 \ell_1 \ell_2 \dot{\theta}_1 \dot{\theta}_2 (-\sin \theta_1 \cos \theta_2 + \cos \theta_1 \sin \theta_2) - g(m_1 + m_2) \ell_1 \sin \theta_1$$

$$+ (m_1 + m_2) \ell_1^2 \ddot{\theta}_1 - m_2 \ell_1 \ell_2 \frac{d}{dt} [\dot{\theta}_2 (\cos \theta_1 \cos \theta_2 + \sin \theta_1 \sin \theta_2)]$$

$$0 = m_2 \ell_1 \ell_2 \dot{\theta}_1 \dot{\theta}_2 (-\cos \theta_1 \sin \theta_2 + \sin \theta_1 \cos \theta_2) - g m_2 \ell_2 \sin \theta_2$$

$$- m_2 \ell_2^2 \ddot{\theta}_2 - m_2 \ell_1 \ell_2 \frac{d}{dt} [\dot{\theta}_1 (\cos \theta_1 \cos \theta_2 + \sin \theta_1 \sin \theta_2)]$$

C. Noether's theorem

Each continuous symmetry generates a conserved quantity

Symmetry: $\mathbf{x}(t) \rightarrow \mathbf{x}'(t')$, $L(\mathbf{x}, \dot{\mathbf{x}}) = L(\mathbf{x}', \dot{\mathbf{x}}') + \dot{\Lambda}(t', \mathbf{x}')$

Continuous symmetry: \exists infinitesimal transformations, $\mathbf{x} \rightarrow \mathbf{x} + \epsilon \mathbf{f}(t, \mathbf{x})$, $t \rightarrow t + \epsilon f(t, \mathbf{x})$

Conserved quantity: $\dot{F}(\mathbf{x}, \dot{\mathbf{x}}) = 0$

(a) $\mathbf{f} \neq 0$, $f = 0$:

$$L(\mathbf{x}, \dot{\mathbf{x}}) = L(\mathbf{x} + \epsilon \mathbf{f}, \dot{\mathbf{x}} + \epsilon \partial_t \mathbf{f} + \epsilon(\dot{\mathbf{x}} \partial) \mathbf{f}) + \mathcal{O}(\epsilon^2)$$

A particular variation: $\epsilon \rightarrow \epsilon(t)$, $\mathbf{x} = \mathbf{x}_{cl}$, $\delta S[\epsilon] = \mathcal{O}(\epsilon^2)$

$$\begin{aligned}\tilde{L}(\epsilon, \dot{\epsilon}) &= L(\mathbf{x} + \epsilon \mathbf{f}, \dot{\mathbf{x}} + \epsilon \partial_t \mathbf{f} + \epsilon (\dot{\mathbf{x}} \partial) \mathbf{f} + \dot{\epsilon} \mathbf{f}) + \mathcal{O}(\epsilon^2) \\ &= \epsilon \left[\frac{\partial L}{\partial \mathbf{x}} \mathbf{f} + \frac{\partial L}{\partial \dot{\mathbf{x}}} \partial_t \mathbf{f} + \frac{\partial L}{\partial \dot{\mathbf{x}}} (\dot{\mathbf{x}} \partial) \mathbf{f} \right] + \frac{\partial L}{\partial \dot{\mathbf{x}}} \dot{\epsilon} \mathbf{f} + \mathcal{O}(\epsilon^2)\end{aligned}$$

Euler-Lagrange equation:

$$\underbrace{\frac{\partial \tilde{L}(\epsilon, \dot{\epsilon})}{\partial \epsilon}}_0 = \frac{d}{dt} \underbrace{\frac{\partial \tilde{L}(\epsilon, \dot{\epsilon})}{\partial \dot{\epsilon}}}_{p_\epsilon}, \quad p_\epsilon = \frac{\partial L}{\partial \dot{\mathbf{x}}} \mathbf{f}$$

Translations: $\mathbf{f}(\mathbf{x}) = \mathbf{n}$, $\mathbf{n}^2 = 1$. $L = \frac{m}{2} \dot{\mathbf{x}}^2 - U(\mathbf{T}\mathbf{x})$, $T = \mathbb{1} - \mathbf{n} \otimes \mathbf{n}$, $p_\epsilon = m \dot{\mathbf{x}} \mathbf{n}$

Rotations: $\mathbf{f}(\mathbf{x}) = \mathbf{n} \times \mathbf{x}$, $\mathbf{n}^2 = 1$. $L = \frac{m}{2} \dot{\mathbf{x}}^2 - U(|\mathbf{x}|)$, $p_\epsilon = m \dot{\mathbf{x}} (\mathbf{n} \times \mathbf{x}) = \mathbf{n} (\mathbf{x} \times m \dot{\mathbf{x}}) = \mathbf{n} L$

(b) $\mathbf{f} = 0$, $f \neq 0$: $t \rightarrow t' = t + \epsilon$, $\mathbf{x}(t) \rightarrow \mathbf{x}(t - \epsilon) = \mathbf{x}(t) - \epsilon \dot{\mathbf{x}}(t)$, $\delta \mathbf{x} = -\epsilon \dot{\mathbf{x}}$

A reparametrization of the time integral of the action with $\epsilon \rightarrow \epsilon(t)$:

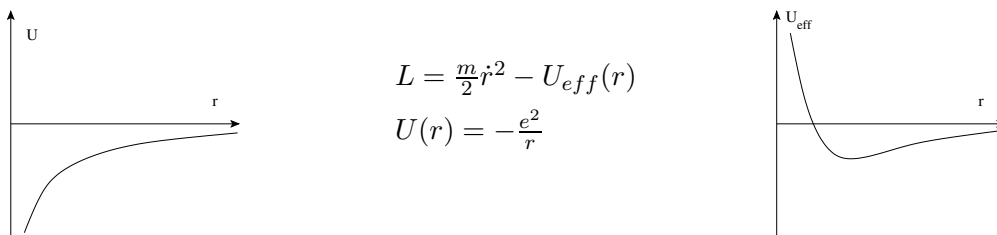
$$\begin{aligned}S[\mathbf{x}] &= \int_{t_i + \epsilon(t_i)}^{t_f + \epsilon(t_f)} \underbrace{\frac{dt'}{1 + \dot{\epsilon}}}_{dt = \frac{dt'}{(\frac{dt'}{dt})}} L(\mathbf{x}(t' - \epsilon), \dot{\mathbf{x}}(t' - \epsilon)) \\ 0 &= - \int_{t_i}^{t_f} dt \left(\epsilon \dot{\mathbf{x}} \frac{\partial L}{\partial \mathbf{x}} + \frac{d}{dt} \epsilon \dot{\mathbf{x}} \frac{\partial L}{\partial \dot{\mathbf{x}}} + \dot{\epsilon} L \right) + \epsilon L(\mathbf{x}(t), \dot{\mathbf{x}}(t)) \Big|_{t_i}^{t_f} \\ &= - \int_{t_i}^{t_f} dt \left[\epsilon \dot{\mathbf{x}} \left(\frac{\partial L}{\partial \mathbf{x}} - \frac{d}{dt} \frac{\partial L}{\partial \dot{\mathbf{x}}} \right) + \dot{\epsilon} L \right] + \epsilon \left(L - \dot{\mathbf{x}} \frac{\partial L}{\partial \dot{\mathbf{x}}} \right) \Big|_{t_i}^{t_f} \\ \epsilon(t) \rightarrow \epsilon \quad H &= \frac{\partial L}{\partial \dot{\mathbf{x}}} \dot{\mathbf{x}} - L \quad \text{is conserved}\end{aligned}$$

D. Examples

1. Spherically symmetric potential:

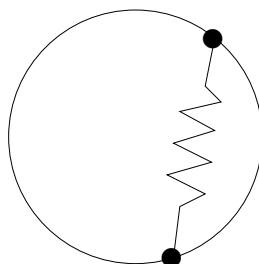
$$\begin{aligned}L &= \frac{m}{2} \dot{\mathbf{x}}^2 - U(|\mathbf{x}|) \\ \mathbf{x} &= r \begin{pmatrix} \sin \theta \cos \phi \\ \sin \theta \sin \phi \\ \cos \theta \end{pmatrix}, \quad \dot{\mathbf{x}} = \dot{r} \begin{pmatrix} \sin \theta \cos \phi \\ \sin \theta \sin \phi \\ \cos \theta \end{pmatrix} + r \begin{pmatrix} \dot{\theta} \cos \theta \cos \phi - \dot{\phi} \sin \theta \sin \phi \\ \dot{\theta} \cos \theta \sin \phi + \dot{\phi} \sin \theta \cos \phi \\ -\dot{\theta} \sin \theta \end{pmatrix} \\ L &= \frac{m}{2} [\dot{r}^2 + r^2 \dot{\theta}^2 + r^2 \dot{\phi}^2 \sin^2 \theta] - U(r) \\ 0 &= \frac{\partial L}{\partial x} - \frac{d}{dt} \frac{\partial L}{\partial \dot{x}} \\ 0 &= r^2 \dot{\phi}^2 \sin \theta \cos \theta - \frac{d}{dt} r^2 \dot{\theta} \quad \rightarrow \quad \text{planar motion : } \theta = \frac{\pi}{2} \\ 0 &= \frac{d}{dt} \frac{\delta L}{\delta \dot{\phi}} = \frac{d}{dt} p_\phi = \frac{d}{dt} m r^2 \dot{\phi} \sin^2 \theta \quad \rightarrow \quad \text{conservation of } p_\phi = m r^2 \dot{\phi} = L_z = \ell \\ 0 &= -U'(r) + m r (\dot{\theta}^2 + \dot{\phi}^2 \sin^2 \theta) - m \ddot{r} = -U'(r) + m r \dot{\phi}^2 - m \ddot{r} \\ &= -U'(r) + \frac{\ell^2}{m r^3} - m \ddot{r} = -U'(r) - \frac{d}{dr} \frac{\ell^2}{2 m r^2} - m \ddot{r} \\ m \ddot{r} &= -U'_{eff}(r), \quad U_{eff}(r) = U(r) + \frac{\ell^2}{2 m r^2}\end{aligned}$$

One-dimensional motion in an effective potential with an centrifugal barrier:



- What can one say about the possibility of falling into the center for $U(r) = -\frac{g}{r^n}$ with $n = 2$ or 3 ?
- Is there circular orbit for $U(r) = -\frac{g_1}{r} - \frac{g_3}{r^3}$?
- What are the stable orbits for $U(r) = -g\frac{e^{-kr}}{r}$?

2. Two particles on a ring: Two point particles of mass m move on a ring of radius r without friction. They are connected by a massless spring of length $\ell < 2r$ and spring constant k .



- (a): Find a continuous symmetry and the corresponding conserved quantity.
 (b): Solve the equation of motion for small oscillations.

- Lagrangian:

$$L = \frac{m}{2}r^2(\dot{\alpha}^2 + \dot{\beta}^2) - \frac{k}{2} \left(2r \sin \frac{\alpha - \beta}{2} - \ell \right)^2$$

- Symmetry: $\alpha \rightarrow \alpha + \phi, \beta \rightarrow \beta + \phi$ (rotation)
- New coordinates: $\Theta = \frac{\alpha + \beta}{2}, \chi = \alpha - \beta, \Theta \rightarrow \Theta + \phi, \chi \rightarrow \chi$

$$\begin{aligned} \alpha &= \Theta + \frac{\chi}{2}, & \beta &= \Theta - \frac{\chi}{2} \\ L &= \frac{m}{2}r^2 \left[\left(\dot{\Theta} + \frac{\dot{\chi}}{2} \right)^2 + \left(\dot{\Theta} - \frac{\dot{\chi}}{2} \right)^2 \right] - \frac{k}{2} \left(2r \sin \frac{\chi}{2} - \ell \right)^2 \\ &= mr^2 \left(\dot{\Theta}^2 + \frac{\dot{\chi}^2}{4} \right) - \frac{k}{2} \left(2r \sin \frac{\chi}{2} - \ell \right)^2 \end{aligned}$$

- Conservation law:

$$p_{\Theta} = \frac{\partial L}{\partial \dot{\Theta}} = 2mr^2\dot{\Theta} = L_z = mr^2(\dot{\alpha} + \dot{\beta})$$

- E.O.M.

$$0 = \frac{\partial L}{\partial x} - \frac{d}{dt} \frac{\partial L}{\partial \dot{x}}$$

$$\delta\Theta : 2mr^2\ddot{\Theta} = 0, \quad \Theta = \Theta_0 + \Omega t$$

$$\delta\chi : \frac{mr^2}{2}\ddot{\chi} = -kr \left(2r \sin \frac{\chi}{2} - \ell \right) \cos \frac{\chi}{2}$$

- Small oscillations: $2r \sin \frac{\chi}{2} \approx \ell$, $2r \sin \frac{\chi_0}{2} = \ell$, $\chi = \chi_0 + \epsilon$

$$\frac{mr^2}{2}\ddot{\epsilon} = -kr \left(2r \sin \frac{\chi_0 + \epsilon}{2} - \ell \right) \cos \frac{\chi_0 + \epsilon}{2} \approx -kr^2 \epsilon \cos^2 \frac{\chi_0}{2}$$

$$\omega^2 = 2\frac{k}{m} \cos^2 \frac{\chi_0}{2} = 2\frac{k}{m} \left[1 - \left(\frac{\ell}{2r} \right)^2 \right]$$

Special cases:

$$\ell \approx 2r : \quad \omega \approx 0 \quad \text{Why?}$$

$$\ell \approx 0 : \quad \omega \approx \sqrt{\frac{2k}{m}}$$

VI. RELATIVISTIC MECHANICS

A. Vectors and tensors

The components of the four-vector, $x^\mu = (ct, \mathbf{x}) = (x^0, \mathbf{x})$, $\mu = 0, 1, 2, 3$, are mixed by Lorentz transformations

Invariant length: to characterize the Lorentz transformations

$$s^2 = x^{02} - \mathbf{x}^2 = x^\mu g_{\mu\nu} x^\nu = xx$$

Metric tensor: to define the scalar product

$$g_{\mu\nu} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

Scalar product:

$$xy = \sum_{\mu\nu} x^\mu g_{\mu\nu} y^\nu$$

To suppress g one uses two representation for each vector u :

- a covariant, u_μ , and
- a contravariant, u^μ :

$$\begin{aligned} u_\mu &= g_{\mu\nu}u^\nu, & u^\mu &= g^{\mu\nu}u_\nu & \rightarrow & \quad xy = x^\mu y_\mu = x_\mu y^\mu \\ u_\mu &= g_{\mu\nu}g^{\nu\rho}u_\rho & \rightarrow & \quad g_{\mu\nu}g^{\nu\rho} = g_\mu{}^\rho = \delta_\mu^\rho \end{aligned}$$

Einstein convention:

$$\sum_\mu (\dots)^\mu (\dots)_\mu \rightarrow (\dots)^\mu (\dots)_\mu$$

Lorentz group: Family of linear transformations

$$x^\mu \rightarrow x'^\mu = \Lambda^\mu{}_\nu x^\nu,$$

preserving the invariant length,

$$xy = x'^\mu \Lambda^\mu{}_{\mu'} g_{\mu\nu} \Lambda^\nu{}_{\nu'} y^{\nu'}, \quad g_{\mu\nu} = \Lambda^{\mu'}{}_\mu g_{\mu'\nu'} \Lambda^{\nu'}{}_\nu.$$

It has 6 dimensions, 3 for spatial rotation,

$$\Lambda = \begin{pmatrix} 1 & \mathbf{0} \\ \mathbf{0} & R \end{pmatrix}, \quad R^{\text{tr}}R = \mathbb{1}$$

and another 3 for boosts: $\mathbf{x} = \mathbf{x}_\parallel + \mathbf{x}_\perp$, $\mathbf{x}_\parallel \mathbf{x}_\perp = \mathbf{v} \mathbf{x}_\perp = 0$.

$$\mathbf{x}' = \alpha(\mathbf{x}_\parallel - \mathbf{v}t) + \gamma \mathbf{x}_\perp, \quad t' = \beta \left(t - \frac{\mathbf{x}_\parallel \mathbf{v}}{c^2} \right)$$

Invariance:

$$\begin{aligned} c^2 t^2 - \mathbf{x}^2 &= c^2 \beta^2 \left(t - \frac{\mathbf{x}_\parallel \mathbf{v}}{c^2} \right)^2 - \alpha^2 (\mathbf{x}_\parallel - \mathbf{v}t)^2 - \gamma \mathbf{x}_\perp^2 \\ &= c^2 t^2 \left(\beta^2 - \alpha^2 \frac{\mathbf{v}^2}{c^2} \right) - \mathbf{x}_\parallel^2 \left(\alpha^2 - \frac{c^2 \mathbf{v}^2}{c^2} \beta^2 \right) + 2\mathbf{v} \mathbf{x}_\parallel t \left(\alpha^2 - \frac{c^2}{c^2} \beta^2 \right) \\ \mathcal{O}(\mathbf{x}_\perp^2) : \gamma &= \pm 1 \rightarrow 1 \quad \leftarrow \quad v = 0 \\ \mathcal{O}(\mathbf{x}_\perp \mathbf{v}) : 0 &= \alpha^2 - \frac{c^2}{c^2} \beta^2 \\ \mathcal{O}(\mathbf{x}_\parallel^2) : -1 &= \frac{c^2 \mathbf{v}^2}{c^2} \beta^2 - \alpha^2 \rightarrow \beta^2 = \frac{\tilde{c}^2}{c^2} \frac{1}{1 - \frac{\mathbf{v}^2}{c^2}} \\ \mathcal{O}(c^2 t^2) : 1 &= \beta^2 - \alpha^2 \frac{\mathbf{v}^2}{c^2} = \frac{\tilde{c}^2}{c^2} \frac{1}{1 - \frac{c^2 \mathbf{v}^2}{c^2 c^2}} \left(1 - \frac{c^2 \mathbf{v}^2}{c^2 c^2} \right) \rightarrow \tilde{c}^2 = c^2 \\ \alpha &= \beta = \frac{1}{\sqrt{1 - \frac{\mathbf{v}^2}{c^2}}} \quad \leftarrow \quad v = 0 \end{aligned}$$

$$\mathbf{x}'_{\parallel} = \frac{\mathbf{x}_{\parallel} - \mathbf{v}t}{\sqrt{1 - \frac{v^2}{c^2}}}, \quad ct' = \frac{ct - \frac{\mathbf{v}\mathbf{x}_{\parallel}}{c}}{\sqrt{1 - \frac{v^2}{c^2}}}$$

Inverse: $\mathbf{v} \rightarrow -\mathbf{v}$

$$\mathbf{x}_{\parallel} = \frac{\mathbf{x}'_{\parallel} + \mathbf{v}t'}{\sqrt{1 - \frac{v^2}{c^2}}}, \quad ct = \frac{ct' + \frac{\mathbf{v}\mathbf{x}'_{\parallel}}{c}}{\sqrt{1 - \frac{v^2}{c^2}}}$$

Exercise: internal consistency of the notation, $\Lambda = \Lambda^{\mu}_{\nu}$, $g = g_{\mu\nu}$, $g^{\text{tr}} = g$,

$$\begin{aligned} g &= \Lambda^{\text{tr}} g \Lambda, \quad \leftrightarrow \quad g_{\mu\nu} = \Lambda^{\mu'}_{\mu} g_{\mu'\nu'} \Lambda^{\nu'}_{\nu} \\ \Lambda^{-1} &= g^{-1} \Lambda^{\text{tr}} g = (g \Lambda g^{-1})^{\text{tr}}, \quad \leftrightarrow \quad \Lambda^{-1\mu}_{\nu} = g^{\mu\mu'} \Lambda^{\nu'}_{\mu'} g_{\nu'\nu} = \Lambda^{\mu}_{\nu'} \quad (\text{orth.}) \\ x'^{\mu} &= (\Lambda x)^{\mu} = \Lambda^{\mu}_{\nu} x^{\nu} \\ x^{\mu} &= (g \Lambda g^{-1})^{\mu}_{\nu} x'^{\nu} = x'^{\nu} \Lambda^{\mu}_{\nu} = (x' \Lambda)^{\mu} \\ x'_{\mu} &= (g \Lambda x)_{\mu} = (g \Lambda g^{-1} g x)_{\mu} = \Lambda_{\mu}^{\nu} x_{\nu} = (\Lambda x)_{\mu} \\ x_{\mu} &= x'^{\nu} g_{\nu\lambda} g^{\lambda\rho} \Lambda_{\rho\mu} = x'_{\lambda} \Lambda^{\lambda}_{\mu} = (x' \Lambda)_{\mu} \end{aligned}$$

N.B. rotations : $\mathbf{x}' = R\mathbf{x}$, $\mathbf{x} = R^{\text{tr}}\mathbf{x}' = \mathbf{x}'R$

contravariant tensor : $T^{\mu_1 \dots \mu_n} = \Lambda^{\mu_1}_{\nu_1} \dots \Lambda^{\mu_n}_{\nu_n} T^{\nu_1 \dots \nu_n}$

covariant tensor : $T_{\mu_1 \dots \mu_n} = \Lambda_{\mu_1}^{\nu_1} \dots \Lambda_{\mu_n}^{\nu_n} T_{\nu_1 \dots \nu_n}$

mixed tensor : $T^{\rho_1 \dots \rho_m}_{\mu_1 \dots \mu_n} = \Lambda^{\rho_1}_{\kappa_1} \dots \Lambda^{\rho_m}_{\kappa_m} \Lambda_{\mu_1}^{\nu_1} \dots \Lambda_{\mu_n}^{\nu_n} T^{\kappa_1 \dots \kappa_m}_{\nu_1 \dots \nu_n}$

Invariant tensor:

$$g_{\mu\nu} = \Lambda^{\mu'}_{\mu} g'_{\mu'\nu'} \Lambda^{\nu'}_{\nu}$$

B. Relativistic generalization of the Newtonian mechanics

Four-velocity: $ds = dx^0 \sqrt{1 - \frac{v^2}{c^2}}$

$$ds^2 = dx^{02} - d\mathbf{x}^2 = dx^{02} \left[1 - \left(\frac{d\mathbf{x}}{dx^0} \right)^2 \right] = dx^{02} \left(1 - \frac{\dot{\mathbf{x}}^2}{c^2} \right)$$

$$ds = dx^0 \sqrt{1 - \frac{v^2}{c^2}}$$

$$u^{\mu} = \frac{dx^{\mu}(s)}{ds} = \dot{x}(s) = \left(\frac{dx^0}{ds}, \frac{d\mathbf{x}}{ds} \right) = \left(\frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}, \frac{\frac{\mathbf{v}}{c}}{\sqrt{1 - \frac{v^2}{c^2}}} \right)$$

Four-acceleration:

$$\dot{u}^{\mu} = \frac{du^{\mu}}{ds}, \quad u^2 = 1 \quad \rightarrow \quad \dot{u}u = 0$$

Four-momentum:

$$p^\mu = mcu^\mu = \left(\frac{mc}{\sqrt{1 - \frac{v^2}{c^2}}}, \frac{m\mathbf{v}}{\sqrt{1 - \frac{v^2}{c^2}}} \right) = \left(\frac{E}{c}, \mathbf{p} \right), \quad p^2 = m^2 c^2$$

N.B. (i) $c \rightarrow \infty$, $\mathbf{p} \rightarrow m\mathbf{v}$, (ii) $v \rightarrow c$, $\mathbf{p} \rightarrow \infty$

Four-force:

$$\frac{dp^\mu}{ds} = \frac{d}{ds} \left(mc \frac{dx^\mu}{ds} \right) = K^\mu$$

Spatial components:

$$\begin{aligned} \frac{dt}{ds} \frac{d}{dt} \left(mc \frac{dt}{ds} \frac{d\mathbf{x}}{dt} \right) &= \mathbf{K} \\ m(v) &= m \frac{dx^0}{ds} = \frac{m}{\sqrt{1 - \frac{v^2}{c^2}}} \\ \frac{d}{dt} \left(m(v) \frac{d\mathbf{x}}{dt} \right) &= \frac{d}{dt} \mathbf{p} = \frac{ds}{dt} \mathbf{K} = \mathbf{F} \end{aligned}$$

Temporal component: (energy equation)

$$\begin{aligned} \frac{d}{ds} \left(mc \frac{dx^0}{ds} \right) &= \frac{d}{ds} \frac{mc}{\sqrt{1 - \frac{v^2}{c^2}}} = K^0 \\ Ku &= 0 \quad \rightarrow \quad \underbrace{K^0}_{\frac{dt}{ds} \frac{d}{dt} cm(v)} \frac{dx^0}{ds} = \underbrace{\mathbf{K}}_{\frac{dt}{ds} \mathbf{F}} \underbrace{\mathbf{u}}_{\frac{dt}{ds} \mathbf{v}} \\ \frac{dm(v)c^2}{dt} &= \mathbf{F}\mathbf{v} \quad \rightarrow \quad m(v)c^2 = \int \mathbf{F}\mathbf{v} dt = \int \mathbf{F} d\mathbf{r} \\ \text{let } \mathbf{F} &= -\nabla\phi \quad \rightarrow \quad E = \underbrace{m(v)c^2}_{cp^0} + \phi \quad \text{is constant} \end{aligned}$$

Energy:

$$\begin{aligned} p^\mu &= \left(\frac{E}{c}, m(v)\mathbf{v} \right), \quad \frac{E^2}{c^2} = \mathbf{p}^2 + m^2 c^2, \quad E(\mathbf{p}) = \pm c \sqrt{\mathbf{p}^2 + m^2 c^2} \\ \frac{\partial |E(\mathbf{p})|}{\partial \mathbf{p}} &= \frac{\mathbf{p}c}{\sqrt{\mathbf{p}^2 + m^2 c^2}} = \frac{\frac{\mathbf{p}}{m}}{\sqrt{1 + \frac{\mathbf{p}^2}{m^2 c^2}}} = \frac{\frac{\mathbf{v}}{\sqrt{1 - \frac{v^2}{c^2}}}}{\sqrt{1 + \frac{v^2}{c^2(1 - \frac{v^2}{c^2})}}} = \mathbf{v}, \quad |\mathbf{v}| \leq c \end{aligned}$$

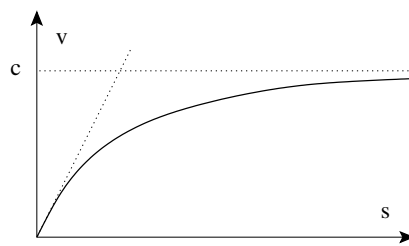
Ex. 1: Constant non-relativistic force

$$F = \frac{d}{dt} p = \frac{d}{dt} \frac{mv}{\sqrt{1 - \frac{v^2}{c^2}}}, \quad x_i = v_i = 0 \quad (\text{non Lorentz inv.!!})$$

$$Ft = \frac{mv}{\sqrt{1 - \frac{v^2}{c^2}}}, \quad 1 - \frac{v^2}{c^2} = \left(\frac{mv}{Ft}\right)^2$$

$$c^2 - v^2 = v^2 \left(\frac{mc}{Ft}\right)^2 \rightarrow c^2 = v^2 \left[1 + \left(\frac{mc}{Ft}\right)^2\right]$$

$$v = \frac{c}{\sqrt{1 + \left(\frac{mc}{Ft}\right)^2}} \approx \begin{cases} t\frac{F}{m} & Ft \ll mc \\ c & Ft \gg mc \end{cases}$$



Ex. 2: Constant relativistic force

$$\frac{dp}{ds} = K$$

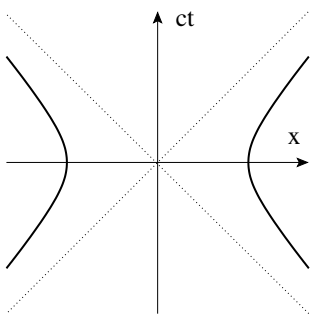
Initial conditions in a co-moving reference frame:

$$x_i = x_0, \quad v_i = 0, \quad x_i = x_0, \quad v_i = 0, \quad u = \dot{x} = (1, \mathbf{0}), \quad \dot{u}u = 0 \rightarrow \dot{u} = \left(0, \frac{\mathbf{a}}{c^2}\right), \quad \dot{u}^2 = -\frac{\mathbf{a}^2}{c^4}$$

Solution of $u^2(s) = 0$:

$$u^\mu = \left(\cosh \frac{a}{c^2}s, \sinh \frac{a}{c^2}s\right)$$

$$x^\mu = \frac{c^2}{a} \left(\sinh \frac{a}{c^2}s, \cosh \frac{a}{c^2}s - 1\right) + (0, x_0)$$



Rindler geometry:

Half of the space-time is unreachable

Thermal radiation of particle-anti particle pairs
on the horizon

⇒ Hawking radiation of black holes

C. Interactions

$$E.M. \quad \ddot{x}_a^\mu = F_a^\mu(x_1, \dots, x_n), \quad a = 1, \dots, n$$

$$C.I. \quad x_a(s_i) = x_{ia}, \quad \dot{x}_a(s_i) = u_a$$

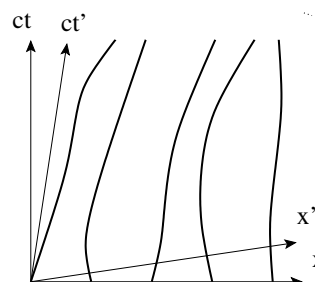
Problems:

1. The initial conditions are imposed

on the spatial hyper-surface, $t = t_i$

and the Lorentz boost mixes into the dynamics:

$$\dot{x}\ddot{x} = 0 \rightarrow u_a F_a = 0$$



2. The four-force, $F_a^\mu(x_1, \dots, x_n)$, represents a superluminal effect

No-Go theorem: there is no relativistic interaction, mediated by a force of the type

$$F_a^\mu(x_1, \dots, x_n) \neq 0$$

e.g.

$$F_a^\mu(x_1, \dots, x_n) = \sum_{b \neq a} (x_a^\mu - x_b^\mu) f((x_a - x_b)^2) \rightarrow (x_a - x_b) \dot{x}_a \neq 0$$

Solution: - distribute degrees of freedom at each space point

- transfer the excitations with a limited speed

\Rightarrow fields, $\phi(t, \mathbf{x})$, appear in physics

D. Variational principle of relativistic mechanics

- Lorentz invariant action:

$$[S] = TML^2T^{-2} = ML^2T^{-1} = [\mathbf{x} \times \mathbf{p}] = [\hbar]$$

$$S = -mc \int_{s_i}^{s_f} ds = -mc \int_{s_i}^{s_f} ds \sqrt{\dot{x}^\mu g_{\mu\nu} \dot{x}^\nu}$$

Reparametrization invariance: $s \rightarrow \tau$:

$$S_\tau = -mc \int_{\tau_{min}}^{\tau_{max}} d\tau \left| \frac{ds}{d\tau} \right| \sqrt{\frac{d\tau}{ds} \frac{dx^\mu}{d\tau} g_{\mu\nu} \frac{dx^\nu}{d\tau} \frac{d\tau}{ds}} = S_s$$

- E.O.M.: $\dot{x}^2 = 1 \implies \tau \neq s$ to allow independent variation of $x^\mu(\tau)$, $x^\mu(\tau) \rightarrow x^\mu(\tau) + \delta x^\mu(\tau)$

$$0 = -mc \frac{d}{d\tau} \frac{\frac{dx^\mu}{d\tau}}{\sqrt{\frac{dx^\rho}{d\tau} g_{\rho\nu} \frac{dx^\nu}{d\tau}}} = -mc \frac{\frac{d^2 x^\mu}{d\tau^2}}{\sqrt{\frac{dx^\rho}{d\tau} g_{\rho\nu} \frac{dx^\nu}{d\tau}}} + mc \frac{\frac{dx^\mu}{d\tau} \frac{d^2 x^\rho}{d\tau^2} g_{\rho\nu} \frac{dx^\nu}{d\tau}}{\left(\frac{dx^\rho}{d\tau} g_{\rho\nu} \frac{dx^\nu}{d\tau} \right)^{3/2}}$$

$$(\tau = s) = -mc \ddot{x}^\mu$$

- The four-momentum:

$$p^\mu = -\frac{\partial L}{\partial \dot{x}_\mu} = mc \dot{x}^\mu$$

- Nonrelativistic notation: $x^\mu = (ct, \mathbf{x})$,

$$S = \int_{t_i}^{t_f} dt \underbrace{(-mc^2) \sqrt{1 - \frac{\mathbf{v}^2}{c^2}}}_{L_t} = -mc^2(t_f - t_i) + \int_{x_i}^{x_f} dt \left[\frac{m}{2} \mathbf{v}^2 + \mathcal{O}\left(\frac{v^4}{c^2}\right) \right]$$

$$\mathbf{p} = \frac{\partial L}{\partial \mathbf{v}} = \frac{m\mathbf{v}}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$E = \frac{\partial L}{\partial \dot{\mathbf{x}}} \dot{\mathbf{x}} - L = \mathbf{p}\mathbf{v} - L$$

$$= \frac{m \left[v^2 + c^2 \left(1 - \frac{v^2}{c^2} \right) \right]}{\sqrt{1 - \frac{v^2}{c^2}}} = \frac{mc^2}{\sqrt{1 - \frac{v^2}{c^2}}} = mc^2 + \frac{v^2}{2m} + \mathcal{O}\left(\frac{v^4}{c^2}\right)$$

Motion in a spherically symmetric potential:

- Coordinates: $x^\mu = (ct, r, \theta, \phi)$

- Action:

$$\begin{aligned} S &= -mc \int ds \sqrt{\dot{x}^\mu g_{\mu\nu} \dot{x}^\nu} - \int dt U(r) = - \int ds [mc \sqrt{\dot{x}^\mu g_{\mu\nu} \dot{x}^\nu} + \dot{t} U(r)] \\ L &= -mc \sqrt{\dot{x}^\mu g_{\mu\nu} \dot{x}^\nu} - \dot{t} U(r) \\ &= -mc \sqrt{c^2 \dot{t}^2 - \dot{r}^2 - r^2 (\dot{\theta}^2 + \sin^2 \theta \dot{\phi}^2)} - \dot{t} U(r) \end{aligned}$$

- $\delta\theta$:

$$r^2 \sin \theta \cos \theta \dot{\phi}^2 = \frac{d}{ds} r^2 \dot{\theta} \quad \rightarrow \quad \theta(s) = \frac{\pi}{2}$$

- Cyclic coordinates: t, ϕ :

$$\begin{aligned} \frac{\partial L}{\partial \dot{t}} &= -mc^3 \dot{t} - U(r) = -mc^2 - E \quad \rightarrow \quad \dot{t} = \frac{(mc^2 + E - U)^2}{m^2 c^6}, \\ \frac{\partial L}{\partial \dot{\phi}} &= mcr^2 \dot{\phi} = \ell, \end{aligned}$$

- Energy equation: $1 = \dot{x}^2$

$$1 = c^2 \dot{t}^2 - \dot{r}^2 - r^2 \dot{\phi}^2 = \frac{(mc^2 + E - U)^2}{m^2 c^4} - \dot{r}^2 - \frac{\ell^2}{m^2 c^2 r^2}$$

- Radial equation of motion:

$$\begin{aligned} \dot{r}^2 &= \dot{t}^2 \left(\frac{dr}{dt} \right)^2 = \frac{(mc^2 + E - U)^2}{m^2 c^4} - \frac{\ell^2}{m^2 c^2 r^2} - 1 \\ \left(\frac{dr}{dt} \right)^2 &= \frac{m^2 c^6}{(mc^2 + E - U)^2} \left[\frac{(mc^2 + E - U)^2}{m^2 c^4} - \frac{\ell^2}{m^2 c^2 r^2} - 1 \right] \\ &= c^2 \left[1 - \frac{\frac{\ell^2 c^2}{r^2} + m^2 c^4}{(mc^2 + E - U)^2} \right] \\ &= c^2 \left[1 - \frac{\frac{\ell^2}{m^2 c^2 r^2} + 1}{\left(1 + \frac{E - U}{mc^2}\right)^2} \right] \end{aligned}$$

- Nonrelativistic limit, $\frac{v}{c} \rightarrow 0$, in the leading $\mathcal{O}\left(\left(\frac{v}{c}\right)^0\right)$ order: ($U, E = \mathcal{O}\left(\left(\frac{v}{c}\right)^0\right)$):

$$\begin{aligned} \left(\frac{dr}{dt} \right)^2 &\approx c^2 \left[1 - \left(\frac{\ell^2}{m^2 c^2 r^2} + 1 \right) \left(1 - 2 \frac{E - U}{mc^2} \right) \right] \approx c^2 \left(-\frac{\ell^2}{m^2 c^2 r^2} + 2 \frac{E - U}{mc^2} \right) \\ &= -\frac{\ell^2}{m^2 r^2} + \frac{2}{m} (E - U) \\ E &\approx \frac{m}{2} \left(\frac{dr}{dt} \right)^2 + \frac{\ell^2}{2mr^2} + U \end{aligned}$$

- Further problems:

1. $\mathcal{O}\left(\left(\frac{v}{c}\right)^2\right)$?

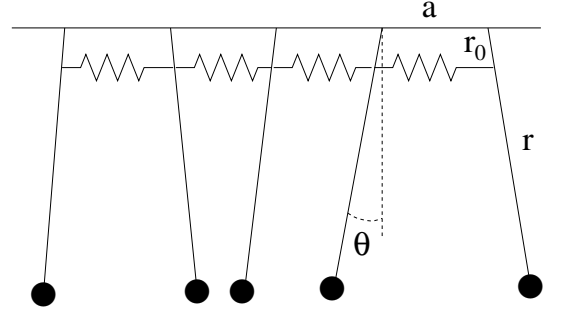
2. Find the equation of motion of the action

$$S = -mc \int ds \sqrt{\dot{x}^\mu g_{\mu\nu} \dot{x}^\nu} - \frac{1}{c} \int ds U(r)$$

VII. FIELD THEORIES

Mechanical analogy: $\theta_n(t) \rightarrow \Phi\theta_n(t) = \phi(t, x_n)$, $\Phi = r_0\sqrt{ak}$, $c = a\frac{r_0}{r}\sqrt{\frac{k}{m}}$, $\lambda = \frac{gr}{a}$

$$\begin{aligned} L &= \sum_n \left[\frac{mr^2}{2} \dot{\theta}_n^2 - \frac{kr_0^2}{2} (\theta_{n+1} - \theta_n)^2 + gr \cos \theta_n \right] \\ &= a \sum_n \left[\frac{1}{2c^2} (\partial_t \phi_n)^2 - \frac{1}{2} \left(\frac{\phi_{n+1} - \phi_n}{a} \right)^2 + \lambda \cos \frac{\phi_n}{\Phi} \right] \\ &\rightarrow \int dx \left[\frac{1}{2c^2} (\partial_t \phi(x))^2 - \frac{1}{2} (\partial_x \phi(x))^2 + \lambda \cos \frac{\phi(x)}{\Phi} \right] \\ S &= \int dt dx \left[\frac{1}{2} \partial_\mu \phi(x) \partial^\mu \phi(x) + \lambda \cos \frac{\phi(x)}{\Phi} \right] \end{aligned}$$



A. Equation of motion

Auxiliary conditions: $\phi(t_i, \mathbf{x}) = \phi_i(\mathbf{x})$, $\phi(t_f, \mathbf{x}) = \phi_f(\mathbf{x})$

Action:

$$S[\phi(\cdot)] = \int_V \underbrace{dt d^3x}_{\frac{1}{c} d^4x} L(\phi, \partial\phi)$$

Variation:

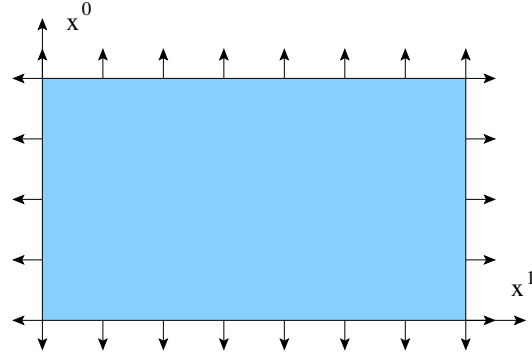
$$\phi(x) \rightarrow \phi(x) + \delta\phi(x), \quad \delta\phi(t_i, \mathbf{x}) = \delta\phi(t_f, \mathbf{x}) = 0$$

$$\begin{aligned} \delta S &= \int_V dt d^3x \left(\frac{\partial L(\phi, \partial\phi)}{\partial \phi} \delta\phi + \frac{\partial L(\phi, \partial\phi)}{\partial \partial_\mu \phi} \delta \partial_\mu \phi \right) + \mathcal{O}(\delta^2 \phi) \\ &= \int_V dt d^3x \left(\frac{\partial L(\phi, \partial\phi)}{\partial \phi} \delta\phi + \frac{\partial L(\phi, \partial\phi)}{\partial \partial_\mu \phi} \partial_\mu \delta\phi \right) + \mathcal{O}(\delta^2 \phi) \\ &= \int_V dt d^3x \left[\frac{\partial L(\phi, \partial\phi)}{\partial \phi} \delta\phi + \partial_\mu \left(\delta\phi \frac{\partial L(\phi, \partial\phi)}{\partial \partial_\mu \phi} \right) - \partial_\mu \frac{\partial L(\phi, \partial\phi)}{\partial \partial_\mu \phi} \delta\phi \right] + \mathcal{O}(\delta^2 \phi) \\ &= \int_{\partial V} ds_\mu \delta\phi \frac{\partial L(\phi, \partial\phi)}{\partial \partial_\mu \phi} + \int_V dt d^3x \delta\phi \left(\frac{\partial L(\phi, \partial\phi)}{\partial \phi} - \partial_\mu \frac{\partial L(\phi, \partial\phi)}{\partial \partial_\mu \phi} \right) + \mathcal{O}(\delta^2 \phi) \end{aligned}$$

$$\begin{array}{ccc} \nearrow & & \nwarrow \\ \int_V dx \partial_\mu j^\mu = \int_{\partial V} ds_\mu j^\mu & & 0 \text{ (local Lagrangian)} \end{array}$$

Euler-Lagrange equation:

$$\frac{\partial L(\phi, \partial\phi)}{\partial \phi_a} - \partial_\mu \frac{\partial L(\phi, \partial\phi)}{\partial \partial_\mu \phi_a} = 0.$$



B. Wave equations for a scalar particle

Schrödinger equation:

$$i\hbar\partial_t\psi(t, \mathbf{x}) = \left[-\frac{\hbar^2}{2m}\Delta + U(\mathbf{x}) \right] \psi(t, \mathbf{x}), \quad L = \psi^* \left[i\hbar\partial_t + \frac{\hbar^2}{2m}\Delta - U(\mathbf{x}) \right] \psi$$

Relativistic generalisation: $\hat{p}_\mu = (\frac{E}{c}, -\mathbf{p}) = -\frac{\hbar}{i}\partial_\mu$, $\hat{p}^\mu = (\frac{E}{c}, \mathbf{p}) = i\hbar\partial^\mu$,

Klein-Gordon equation: $p^\mu = mc\dot{x}^\mu$, $p^2 = m^2c^2$:

$$0 = (\hat{p}^2 - m^2c^2)\phi = -\hbar^2 \left(\partial_\mu\partial^\mu + \frac{m^2c^2}{\hbar^2} \right) \phi,$$

$$0 = \left(\square + \frac{1}{\lambda_C^2} \right) \phi, \quad \lambda_C = \frac{\hbar}{mc} \quad (\text{Compton wavelength})$$

with interaction:

$$\text{real } L = \frac{1}{2}(\partial\phi)^2 - \frac{1}{2\lambda_C^2}\phi^2 - U(\phi)$$

$$\text{complex } L = \partial\phi^*\partial\phi - \frac{1}{\lambda_C^2}\phi^*\phi - V(\phi^*\phi)$$

Free particle: $U(\phi) = \frac{m^2c^2}{2\hbar^2}\phi^2$, $V(\phi^*\phi) = \frac{m^2c^2}{\hbar^2}\phi^*\phi$, $\phi(x) = e^{-\frac{i}{\hbar}p_\mu x^\mu}$,

$$0 = \left(\partial_\mu\partial^\mu + \frac{m^2c^2}{\hbar^2} \right) e^{-\frac{i}{\hbar}p_\mu x^\mu}$$

$$0 = p^2 - \frac{m^2c^2}{\hbar^2}$$

$$\phi(x) = e^{\mp i p_\mu x^\mu}, \quad p_0 = \omega_p = \sqrt{\frac{m^2c^2}{\hbar^2} + \mathbf{p}^2}$$

C. Electrodynamics

Degrees of freedom: charge, $x_a^\mu(s)$, $a = 1, \dots, n$, EM field, $A^\mu(x)$

Gauge invariance: $A_\mu \rightarrow A_\mu + \partial_\mu\alpha$, $F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu \rightarrow \partial_\mu A_\nu + \partial_\mu\partial_\nu\alpha - \partial_\nu A_\mu - \partial_\nu\partial_\mu\alpha = F_{\mu\nu}$

EM field:

Lagrangian:

1. $L_A = \mathcal{O}((\partial_0 A_\mu)^2)$

2. Lorentz invariance

3. gauge invariance

$$L_A = -\frac{1}{16\pi} F^{\mu\nu} F_{\mu\nu}$$

Full action:

$$\begin{aligned} S &= -c \sum_n m_n \int ds_n - \frac{e}{c} \int dt d^3x j^\mu(x) A_\mu(x) - \frac{1}{16\pi} \int dt d^3x F_{\mu\nu}(x) F^{\mu\nu}(x) \\ &= -c \sum_n m_n \int ds_n - \frac{e}{c^2} \int d^4x j^\mu(x) A_\mu(x) - \frac{1}{16\pi c} \int d^4x F_{\mu\nu}(x) F^{\mu\nu}(x), \end{aligned}$$

Electric current:

$$\begin{aligned} j^\mu(x) &= c \sum_a \int ds \delta(x - x_a(s)) \dot{x}^\mu \\ &= c \sum_a \int ds \delta(\mathbf{x} - \mathbf{x}_a(s)) \delta(x^0 - x_a^0(s)) \dot{x}^\mu \\ &= c \sum_a \delta(\mathbf{x} - \mathbf{x}_a(s)) \frac{\dot{x}^\mu}{|\dot{x}^0|} \\ &= \underbrace{\sum_a \delta(\mathbf{x} - \mathbf{x}_a(s))}_{\rho(\mathbf{x})} \frac{dx^\mu}{dt} \\ &= (c\rho, \mathbf{j}) = (c\rho, \rho\mathbf{v}) = \rho \frac{ds}{dt} \dot{x}^\mu \end{aligned}$$

Current conservation:

$$\begin{aligned} \partial_\mu j^\mu &= \partial_t \rho + \nabla \cdot \mathbf{j} \\ &= \sum_a [-\mathbf{v}_a(t) \nabla \delta(\mathbf{x} - \mathbf{x}_a(t)) + \nabla \delta(\mathbf{x} - \mathbf{x}_a(t)) \mathbf{v}_a(t)] = 0 \end{aligned}$$

$$\begin{aligned} S &= -c \sum_n m_n \int ds_n - \frac{e}{c^2} \int d^4x j^\mu(x) A_\mu(x) - \frac{1}{16\pi c} \int d^4x F_{\mu\nu}(x) F^{\mu\nu}(x) \\ &\rightarrow -c \sum_n m_n \int ds_n - \frac{e}{c^2} \int d^4x j^\mu(x) [A_\mu(x) + \partial_\mu \alpha(x)] - \frac{1}{16\pi c} \int d^4x F_{\mu\nu}(x) F^{\mu\nu}(x) \\ &= -c \sum_n m_n \int ds_n - \frac{e}{c^2} \int d^4x [j^\mu(x) A_\mu(x) - \partial_\mu j^\mu(x) \alpha(x)] - \frac{1}{16\pi c} \int d^4x F_{\mu\nu}(x) F^{\mu\nu}(x) = S \end{aligned}$$

Maxwell's equation:

$$\begin{aligned} S_A &= -\frac{e}{c^2} \int d^4x j^\mu A_\mu - \frac{1}{16\pi c} \int d^4x (\partial_\mu A_\nu - \partial_\nu A_\mu) (\partial^\mu A^\nu - \partial^\nu A^\mu) \\ c \frac{\delta}{\delta A_\nu} : \quad \frac{e}{c} j^\nu &= \frac{1}{4\pi} \partial_\mu (\partial^\mu A^\nu - \partial^\nu A^\mu) \\ &= \frac{1}{4\pi} \partial_\mu F^{\mu\nu} \end{aligned}$$

Mechanical E.O.M.: $x(s) \rightarrow x(\tau)$ to avoid $\dot{x}^2(s) = 1$

$$S_{ch} = - \sum_n \int d\tau \left[m_n c \sqrt{\dot{x}^\mu(\tau) g_{\mu\nu} \dot{x}^\nu(\tau)} + \frac{e}{c} \dot{x}_n^\mu(\tau) A_\mu(x_n(\tau)) \right]$$

$$\frac{\delta}{\delta x^\mu} : 0 = -\frac{e}{c} \dot{x}_n^\nu(\tau) \partial_\mu A_\nu(x_n(\tau)) - \frac{d}{d\tau} \left[-mc \frac{\dot{x}_n^\mu(\tau)}{\sqrt{\dot{x}^\mu(\tau) g_{\mu\nu} \dot{x}^\nu(\tau)}} - \frac{e}{c} A_\mu(x_n(\tau)) \right]$$

$$= mc \frac{\ddot{x}_n^\mu(\tau)}{\sqrt{\dot{x}^2(\tau)}} - \frac{e}{c} \dot{x}_n^\nu(\tau) [\partial_\mu A_\nu(x_n(\tau)) - \partial_\nu A_\mu(x_n(\tau))] + mc \frac{\dot{x}_n^\mu(\tau)}{[\dot{x}^2(\tau)]^{3/2}} \ddot{x}^\mu(\tau) \dot{x}_\mu(\tau)$$

$$\tau \rightarrow s : mc \ddot{x}_n^\mu(s) = \frac{e}{c} F_{\mu\nu} \dot{x}_n^\nu(s)$$

Bianchi identity : $\partial_\mu \partial_\nu A_\rho = \partial_\nu \partial_\mu A_\rho$

$$\partial_\rho F_{\mu\nu} + \partial_\nu F_{\rho\mu} + \partial_\mu F_{\nu\rho} = 0$$

Maxwell: $(\mathbf{E}, \mathbf{H}) \rightarrow A_\mu$, the first unification in physics, $A^\mu = (\phi, \mathbf{A})$, $A_\mu = (\phi, -\mathbf{A})$

$$\mathbf{E} = -\partial_0 \mathbf{A} - \nabla \phi = -\frac{1}{c} \partial_t \mathbf{A} - \nabla \phi,$$

$$\mathbf{H} = \nabla \times \mathbf{A}.$$

Inversion:

$$\epsilon_{jkl} H_\ell = \epsilon_{jkl} \epsilon_{lmn} \nabla_m A_n = (\delta_{jm} \delta_{kn} - \delta_{jn} \delta_{km}) \nabla_m A_n = \nabla_j A_k - \nabla_k A_j = -F_{jk}$$

Field strength:

$$F_{\mu\nu} = \begin{pmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & -H_z & H_y \\ -E_y & H_z & 0 & -H_x \\ -E_z & -H_y & H_x & 0 \end{pmatrix}, \quad F^{\mu\nu} = \begin{pmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & -H_z & H_y \\ E_y & H_z & 0 & -H_x \\ E_z & -H_y & H_x & 0 \end{pmatrix}$$

Dual field strength:

$$\tilde{F}_{\mu\nu} = \frac{1}{2} \epsilon_{\mu\nu\rho\sigma} F^{\rho\sigma}$$

$$\tilde{F}_{0j} = -\frac{1}{2} \epsilon_{jkl} F^{kl} = \frac{1}{2} \epsilon_{jkl} \epsilon_{klm} H_m = H_j \quad (\epsilon_{123} = -\epsilon^{123} = -1)$$

$$\tilde{F}_{jk} = -\epsilon_{jkl} F^{\ell 0} = \epsilon_{jkl} E_\ell$$

$$\tilde{F}_{\mu\nu} = \begin{pmatrix} 0 & H_x & H_y & H_z \\ -H_x & 0 & E_z & -E_y \\ -H_y & -E_z & 0 & E_x \\ -H_z & E_y & -E_x & 0 \end{pmatrix}, \quad \tilde{F}^{\mu\nu} = \begin{pmatrix} 0 & -H_x & -H_y & -H_z \\ H_x & 0 & E_z & -E_y \\ H_y & -E_z & 0 & E_x \\ H_z & E_y & -E_x & 0 \end{pmatrix}$$

Inhomogeneous Maxwell equations:

$$\frac{4\pi}{c} j^0 = \nabla_j F^{j0}, \quad \rightarrow \quad 4\pi\rho = \nabla \cdot \mathbf{E}$$

$$\frac{4\pi}{c}j^k = \partial_0 F^{0k} + \nabla_j F^{jk} \quad \rightarrow \quad \frac{4\pi}{c}\mathbf{j} = -\frac{1}{c}\partial_t \mathbf{E} + \nabla \times \mathbf{H}$$

Homogeneous Maxwell equations:

$$\begin{aligned} 0 &= \partial_\mu \tilde{F}^{\mu\nu} \\ 0 &= \nabla_j \tilde{F}^{j0} = \nabla \mathbf{H}, \\ 0 &= \partial_0 \tilde{F}^{0k} + \nabla_j \tilde{F}^{jk} = -\left(\frac{1}{c}\partial_t \mathbf{H} + \nabla \times \mathbf{E}\right) \end{aligned}$$

D. Noether theorem

There is a conserved current for each continuous symmetry

Symmetry: invariance of the E.O.M. which is derived from the action

$$x^\mu \rightarrow x'^\mu, \quad \phi_a(x) \rightarrow \phi'_a(x) \quad \rightarrow \quad L(\phi, \partial\phi) \rightarrow L(\phi', \partial'\phi') + \partial'_\mu \Lambda^\mu$$

External and internal spaces:

$$\phi_a(x) : \underbrace{\mathbb{R}^4}_{\text{external space}} \rightarrow \underbrace{\mathbb{R}^n}_{\text{internal space}} .$$

Continuous symmetry: \exists infinitesimal symmetry transformations

- External symmetry: $x^\mu \rightarrow x^\mu + \delta x^\mu$, e.g. Poincare group
- Internal symmetry: $\phi_a(x) \rightarrow \phi_a(x) + \delta\phi_a(x)$, e.g. $\phi(x) \rightarrow e^{i\alpha}\phi(x)$ for a complex field

Conserved current: $\partial_\mu j^\mu = 0$, conserved charge: $Q(t)$:

$$\partial_0 Q(t) = \partial_0 \int_V d^3x j^0 = - \int_V d^3x \partial_\nu j^\nu = - \int_{\partial V} ds \cdot \mathbf{j}$$

Internal symmetry:

$$\delta x^\mu = 0, \quad \delta\phi_a(x) = \epsilon\tau_{ab}\phi_b(x).$$

Symmetry:

$$L(\phi, \partial\phi) = L(\phi + \epsilon\tau\phi, \partial\phi + \epsilon\tau\partial\phi) + \mathcal{O}(\epsilon^2).$$

New field variable: $\epsilon(x)$, $\phi(x) = \phi_{cl}(x) + \epsilon(x)\tau\phi_{cl}(x)$, $\frac{\delta S[\phi_{cl}]}{\delta\phi} = 0$

Linearized Lagrangian for $\epsilon(x)$ ($\epsilon = 0$ is a solution!):

$$\begin{aligned} L(\epsilon, \partial\epsilon) &= L(\phi_{cl} + \epsilon\tau\phi, \partial\phi_{cl} + \partial\epsilon\tau\phi + \epsilon\tau\partial\phi) \\ &= \frac{\partial L(\phi_{cl}, \partial\phi_{cl})}{\partial\phi} \epsilon\tau + \frac{\partial L(\phi_{cl}, \partial\phi_{cl})}{\partial\partial_\mu\phi} [\partial_\mu\epsilon\tau\phi + \epsilon\tau\partial_\mu\phi] + \mathcal{O}(\epsilon^2) \end{aligned}$$

Symmetry: $\frac{\partial L}{\partial \phi} \epsilon \tau \phi + \frac{\partial L}{\partial \partial_\mu \phi} \epsilon \tau \partial_\mu \phi = 0 \rightarrow \epsilon$ is a cyclic field:

$$\begin{aligned} 0 &= \frac{\partial L(\epsilon, \partial \epsilon)}{\partial \epsilon} - \partial_\mu \frac{\partial L(\epsilon, \partial \epsilon)}{\partial \partial_\mu \epsilon} \\ J_\epsilon^\mu &= \frac{\partial L(\epsilon, \partial \epsilon)}{\partial \partial_\mu \epsilon} = \frac{\partial L(\phi_{cl}, \partial \phi_{cl})}{\partial \partial_\mu \phi} \tau \phi \\ \partial_\mu J_\epsilon^\mu &= 0 \end{aligned}$$

1. Independent conserved current for each independent direction in the symmetry group
2. Defined up to a multiplicative constant

Examples:

1. n -component real scalar field: ϕ_a , $a = 1, \dots, n$, $G = O(n)$,

$$\begin{aligned} L &= \frac{1}{2} (\partial \phi)^2 - V(\phi^2) \\ \delta \phi &= \epsilon^a \tau^a \phi \\ J_\mu^a &= -\partial_\mu \phi \tau^a \phi \end{aligned}$$

2. Single complex scalar field: $\phi = \frac{1}{\sqrt{2}}(\phi_1 + i\phi_2)$, $G = U(1)$, $\phi(x) \rightarrow e^{i\alpha} \phi(x)$

$$\begin{aligned} L &= \frac{1}{2} \partial_\mu \phi_1 \partial^\mu \phi_1 + \frac{1}{2} \partial_\mu \phi_2 \partial^\mu \phi_2 - \frac{m^2}{2} (\phi_1^2 + \phi_2^2) - V\left(\frac{1}{2}(\phi_1^2 + \phi_2^2)\right) \\ &= \partial_\mu \phi^* \partial^\mu \phi + \partial_\mu \phi^* \partial^\mu \phi - m^2 \phi^\dagger \phi - V(\phi^\dagger \phi) \end{aligned}$$

Field variable:

(a) $\begin{pmatrix} \phi \\ \phi^* \end{pmatrix}$:

$$\begin{aligned} \begin{pmatrix} \phi \\ \phi^* \end{pmatrix} &: \begin{pmatrix} \phi \\ \phi^* \end{pmatrix} \rightarrow \begin{pmatrix} e^{i\alpha} \phi \\ e^{-i\alpha} \phi^* \end{pmatrix}, \quad \delta \begin{pmatrix} \phi \\ \phi^* \end{pmatrix} = i\alpha \begin{pmatrix} \phi \\ -\phi^* \end{pmatrix} = \alpha \tau \begin{pmatrix} \phi \\ \phi^* \end{pmatrix}, \quad \tau = i \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \\ J &= -\frac{\partial L}{\partial \partial_\mu \phi} \tau \phi = -i \left(\frac{\partial L}{\partial \partial_\mu \phi} \phi - \frac{\partial L}{\partial \partial_\mu \phi^*} \phi^* \right) = -i(\partial_\mu \phi^* \phi - \phi^* \partial_\mu \phi) = i \phi^* \overleftrightarrow{\partial}_\mu \phi \end{aligned}$$

(b) $\begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix}$:

$$\begin{aligned} \begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix} &: \begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix} \rightarrow e^{i\alpha} \phi = \frac{1}{\sqrt{2}} [\cos \alpha \phi_1 - \sin \alpha \phi_2 + i(\cos \alpha \phi_2 + \sin \alpha \phi_1)] \\ \delta \begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix} &= \alpha \begin{pmatrix} -\phi_2 \\ \phi_1 \end{pmatrix} = \alpha \tau \begin{pmatrix} \phi_1 \\ \phi_2 \end{pmatrix}, \quad \tau = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \\ J &= -\frac{\partial L(\phi, \partial \phi_1)}{\partial \partial_\mu \phi} \tau \phi = -\left(-\frac{\partial L}{\partial \partial_\mu \phi_1} \phi_2 + \frac{\partial L}{\partial \partial_\mu \phi_2} \phi_1 \right) = \partial_\mu \phi_1 \phi_2 - \partial_\mu \phi_2 \phi_1 \\ &= \frac{i}{2} [\partial_\mu (\phi_1 + i\phi_2)^* (\phi_1 + i\phi_2) - (\phi_1 + i\phi_2)^* \partial_\mu (\phi_1 + i\phi_2)] = -i(\partial_\mu \phi^* \phi - \phi^* \partial_\mu \phi) \end{aligned}$$

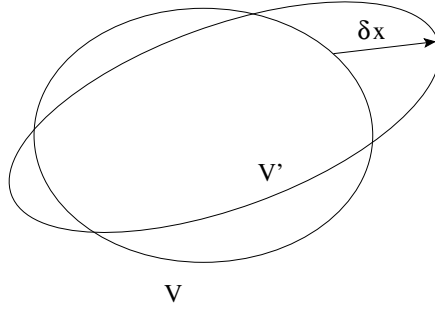
3. n -component complex scalar field: ϕ_a , $a = 1, \dots, n$, $G = U(n)$

$$\begin{aligned} L &= \partial\phi^\dagger\partial\phi - V(\phi^\dagger\phi) \\ \delta\phi &= \epsilon^a\tau^a\phi, \quad \delta\phi^\dagger = \epsilon^a(\phi\tau^a)^\dagger = -\epsilon^a\phi^\dagger\tau^a \\ J_\mu^a &= -\partial_\mu\phi^\dagger\tau^a\phi + \partial_\mu\phi(\tau^a)^\text{tr}\phi^\dagger = -\partial_\mu\phi^\dagger\tau^a\phi + \phi^\dagger\tau^a\partial_\mu\phi = \phi^\dagger\tau^a\overleftrightarrow{\partial}_\mu\phi \end{aligned}$$

External symmetry:

Translations:

- Action is rewritten in terms of $x^\mu \rightarrow x'^\mu = x^\mu + \epsilon^\mu$
- $x \rightarrow x' + \epsilon$, $\phi(x) \rightarrow \phi'(x) = \phi(x) + \delta\phi(x)$, $\delta\phi(x) = -\epsilon^\mu\partial_\mu\phi(x)$, $S \rightarrow S' = S$



$$\begin{aligned} 0 &= \int_V \delta L(\phi(x), \partial\phi(x)) + \int_{V'-V} dx L(\phi(x), \partial\phi(x)) \\ &= \int_V \delta L(\phi(x), \partial\phi(x)) + \int_{\partial V} dS_\nu \epsilon^\nu L(\phi(x), \partial\phi(x)) \\ &= - \int_V dx \epsilon^\nu \partial_\nu \phi \left(\frac{\partial L(\phi, \partial\phi)}{\partial\phi} - \partial_\mu \frac{\partial L(\phi, \partial\phi)}{\partial\partial_\mu\phi} \right) \leftarrow 0 \text{ E.O.M.} \\ &\quad \int_{\partial V} dS_\mu \left[-\epsilon^\nu \partial_\nu \phi \frac{\partial L(\phi, \partial\phi)}{\partial\partial_\mu\phi} + \epsilon^\mu L(\phi, \partial\phi) \right] \end{aligned}$$

- Translation in direction ν :

$$0 = \int_{\partial V} dS_\mu \left[-\partial_\nu \phi \frac{\partial L(\phi, \partial\phi)}{\partial\partial_\mu\phi} + g_\nu^\mu L(\phi, \partial\phi) \right]$$

- V is arbitrary: The energy momentum tensor

$$T^{\mu\nu} = \frac{\partial L}{\partial\partial_\nu\phi} \partial^\mu\phi - g^{\mu\nu} L$$

is conserved

$$\partial_\mu T^{\mu\nu} = 0$$

- "Charge" of the translation ϵ^ν : energy momentum

$$P^\mu = \int d^3x T^{0\mu}$$

- Parameterization:

$$T^{\mu\nu} = \begin{pmatrix} \epsilon & c\mathbf{p} \\ \frac{1}{c}\mathbf{S} & \sigma \end{pmatrix}$$

ϵ = energy density

\mathbf{p} = momentum density

\mathbf{S} = energy flux density

σ^{jk} = momentum flux p^k in the direction j

(c is restored).